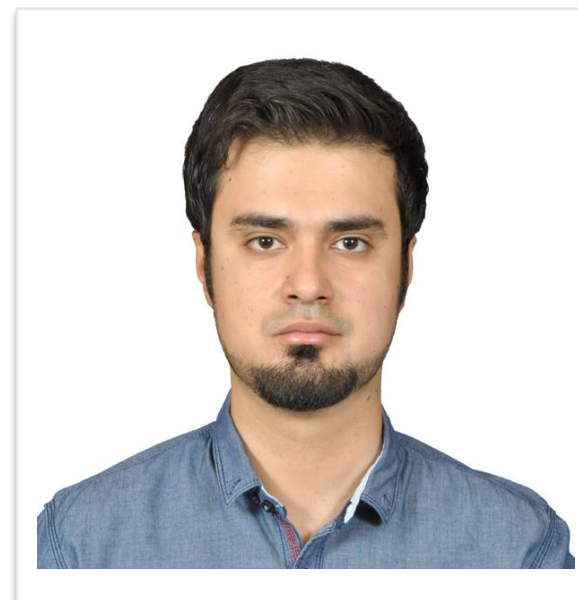


An Application of Physics Informed Recurrent Neural Networks to Structural Dynamics

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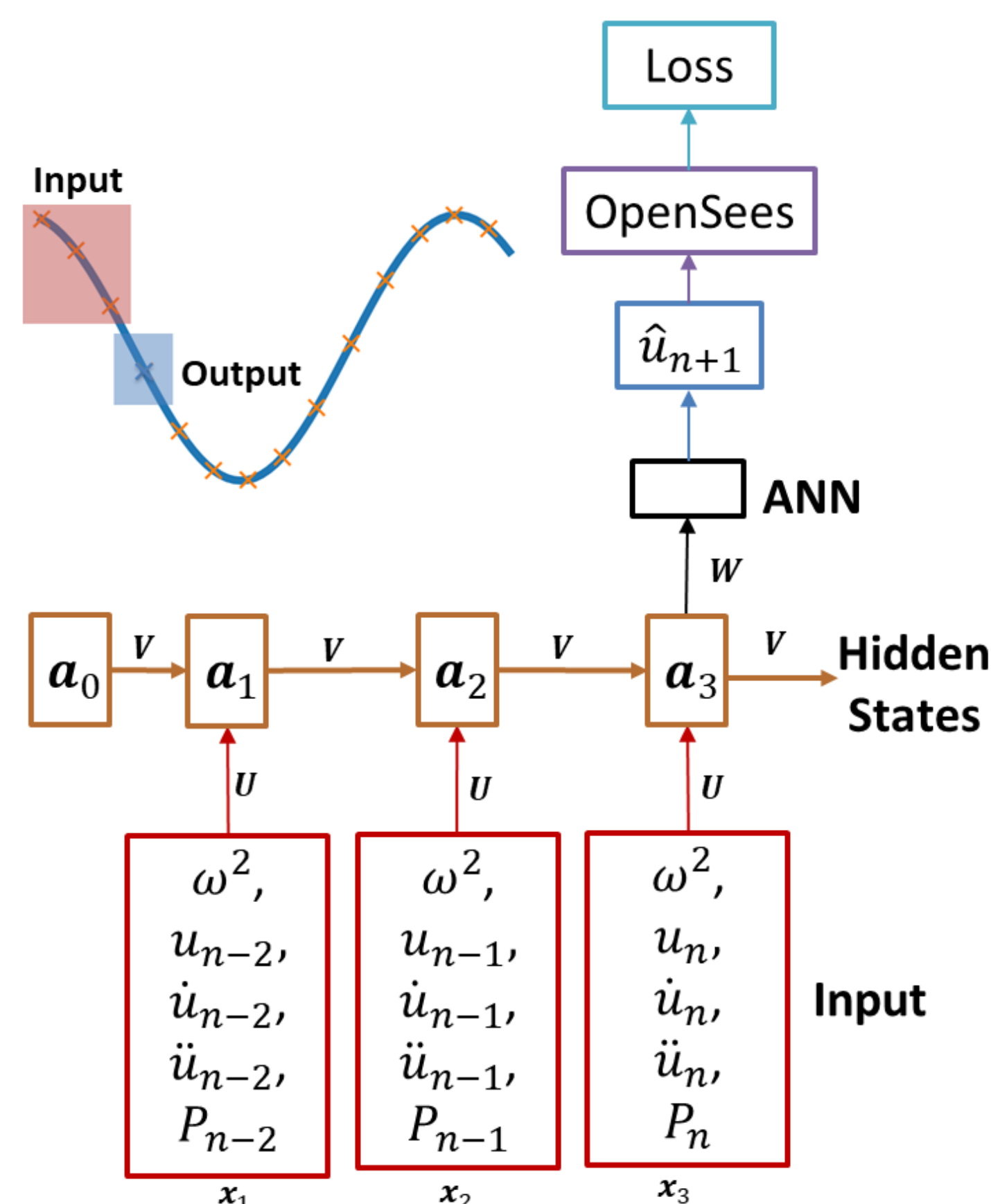
Initial Input and Static Deformation scaling, combined with unitless loss functions, greatly improve RNN performance in structural dynamics.

Introduction

- Neural Networks (NN) structural dynamics modeling can help in improved efficiency and speed.
- Physics-informed neural networks enhance DL learning by integrating physical laws.
- Our research leverages RNNs with tailored loss functions for structural dynamics response, emphasizing loss selection and data scaling importance.

Physics Informed RNN

- RNNs effectively estimate structural behavior by analyzing data over time.
- RNN weights $\{U, V, W\}$ are refined using previous input information, x to estimate future displacement.
- RNN estimations rely on input data preprocessing (data/ feature scaling) and loss normalization, impacting weight fine-tuning, especially when units are involved for uniform learning.
- Physics is embedded in the learning process through OpenSees.



Loss Function implementation

Unitless loss for unitless comparison and consistent learning

$$\text{Data-driven loss } (L_D) \quad L_D = \frac{1}{N} \sum_{n=1} (\hat{u}_n - u_n)^2$$

$$\tilde{L}_D = \frac{1}{N} \sum_{n=1} \left| \frac{\hat{u}_n - u_n}{u_0} \right|$$

$$P_u = m\ddot{u} + c\dot{u} + k\hat{u}$$

Residual loss (L_R)

$$L_R = \frac{1}{N} \sqrt{(P_u^T P_u)}$$

$$\tilde{L}_R = \frac{1}{N} \sqrt{\left(\frac{P_u}{ku_0} \right)^T \left(\frac{P_u}{ku_0} \right)}$$

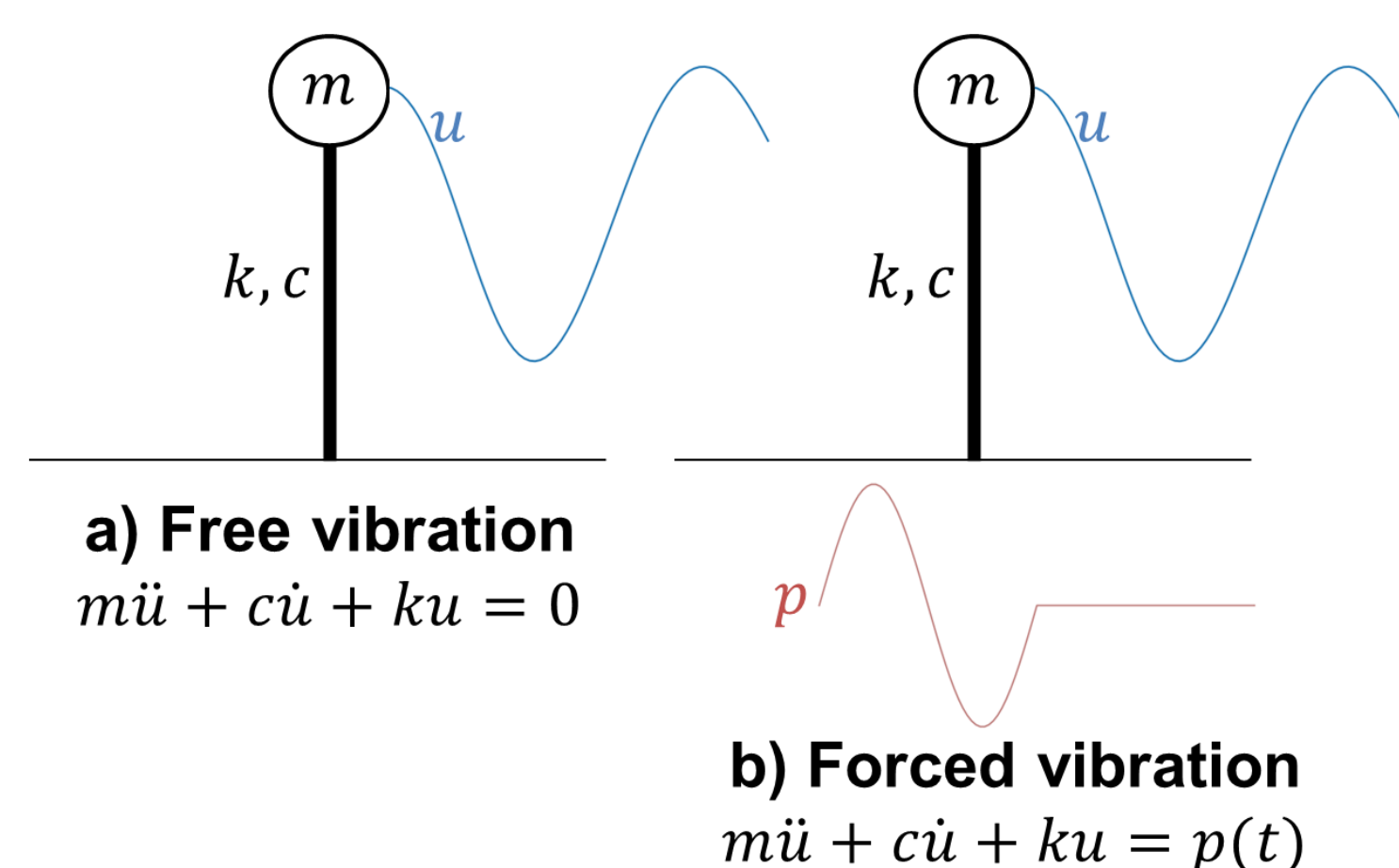
Energy loss (L_E)

$$L_E = \frac{1}{N} |(\hat{u} - u)^T P_u|$$

$$\tilde{L}_E = \frac{1}{N} \left| \left(\frac{\hat{u} - u}{u_0} \right)^T \left(\frac{P_u}{ku_0} \right) \right|$$

Step-by-Step implementation

- RNN implementation for free-response with initial displacement
- RNN implementation for forced vibration with trigonometric, triangle, and constant loads.



Performance Metric

Evaluated RNN model performance using the average \overline{MAPE} across unique time series test files.

$$\overline{MAPE} = \frac{1}{J} \sum \left\{ \frac{1}{N} \sum \left(\left| \frac{\hat{u}_n - u_n}{u_0} \right| \right) \right\}$$

References

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Feature scaling

Min-max Scaling (MMS)

$$x' = \frac{x - x_{min}}{x_{max} - x_{min}} + 1$$

Initial-Input Scaling (IIS)

$$x' = \frac{x}{x_0}$$

Static Deformation Scaling (SD)

$$p' = \frac{p}{p_0}, u' = \frac{u}{u_{st}}, \dot{u}' = \frac{\dot{u}}{p_0 / \sqrt{km}}$$

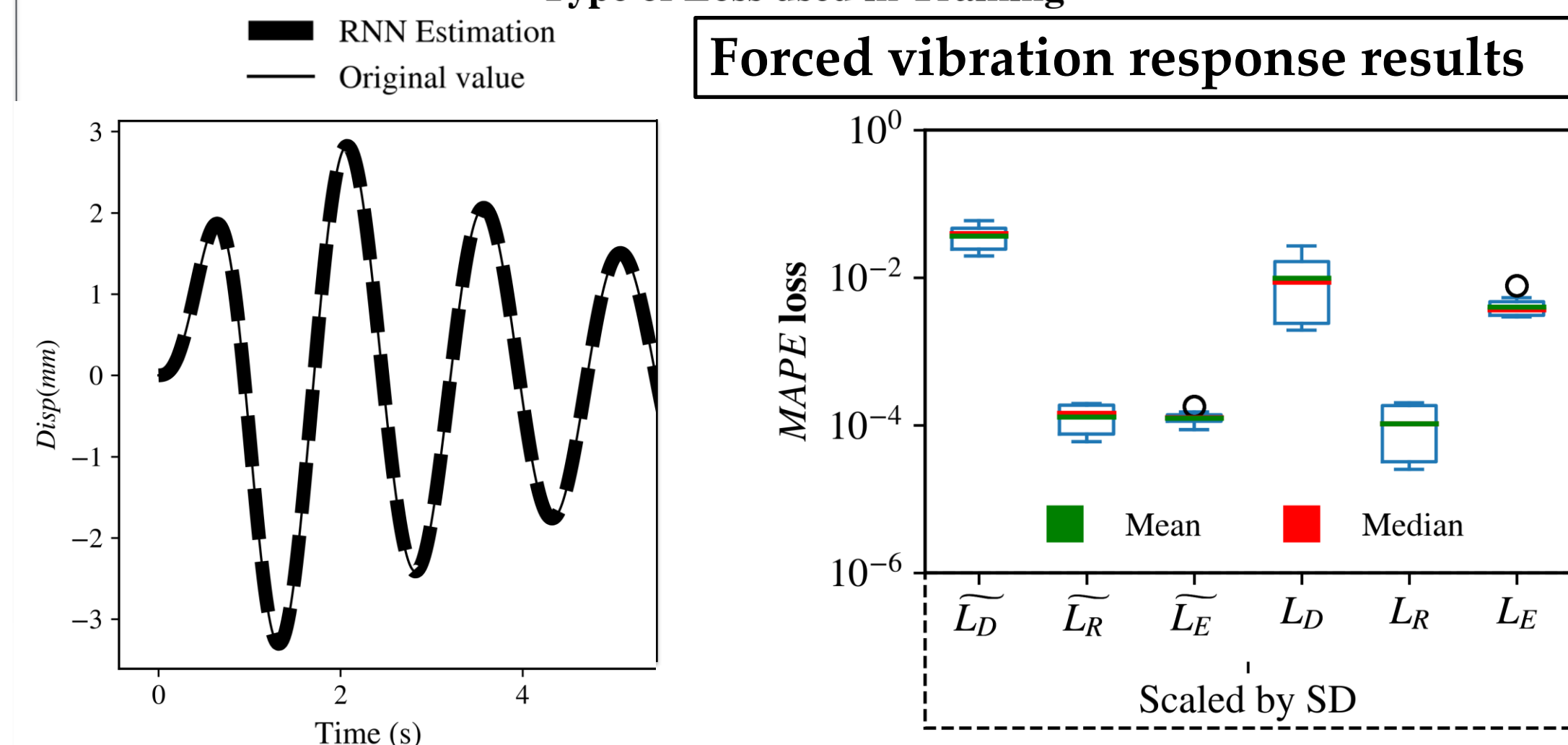
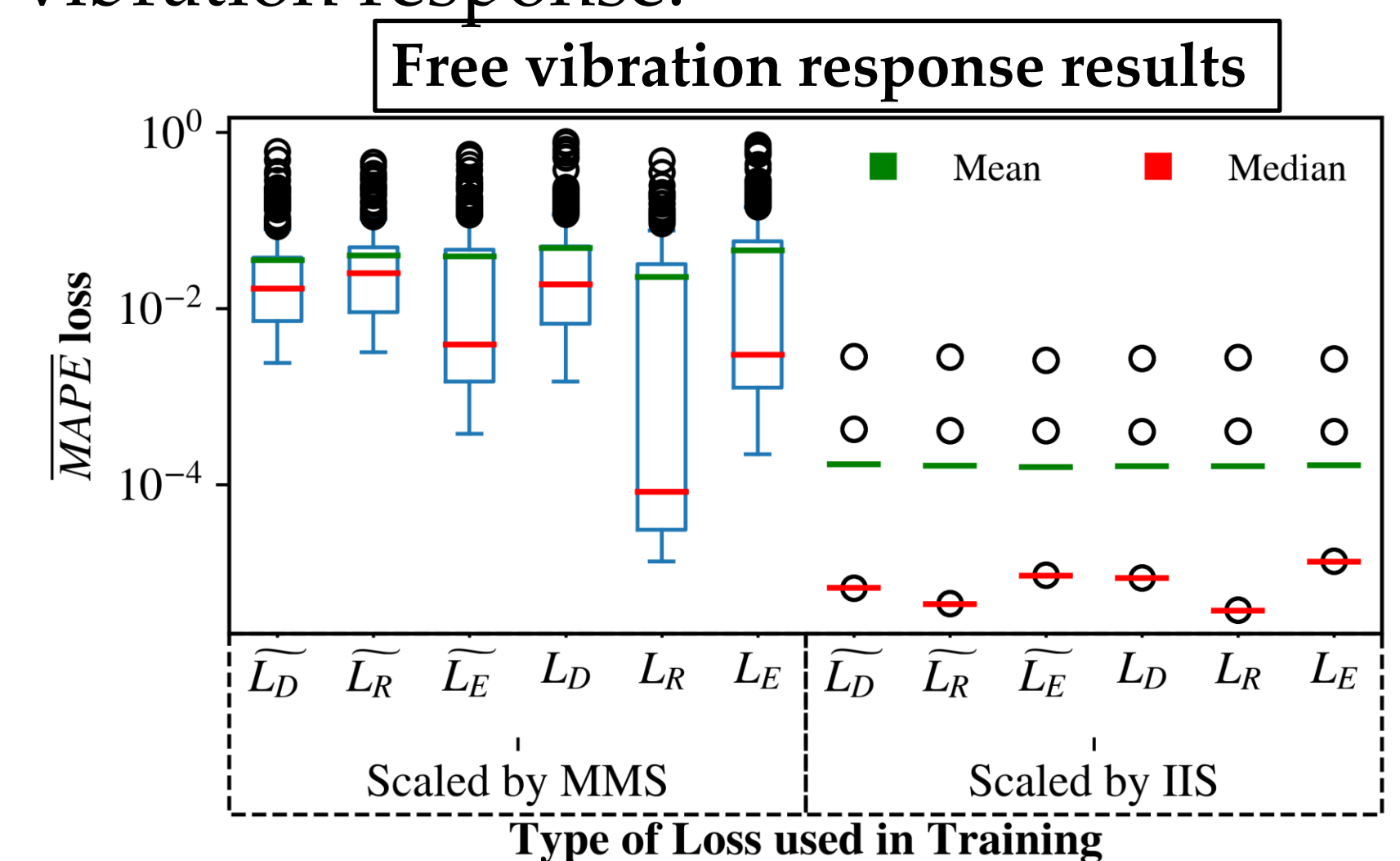
(Forced Vibration and Ground motions)

$$\ddot{u}' = \frac{\ddot{u}}{p_0 / m}$$

$$\omega^{2'} = \frac{\omega^2}{(p_0 / m) / u_{st}}, u_{st}' = \frac{p_0}{k}$$

Results

- IIS scaling has reduced variation in free-vibration response compared to MMS scaling.
- Smaller time step enhances outlier performance in IIS.
- Unitless loss functions yield comparable results for MMS and IIS scaling techniques but have less variance overall.
- SD scaling performs the best for forced vibration response.



Conclusions

- Improved performance of RNN models with IIS or SD over MMS scaling.
- Unitless loss competes closely with unit-dependent losses, with less variability for structural dynamics applications.
- Further research is needed with more complex models such as ground motions or multi-degree of freedom systems.