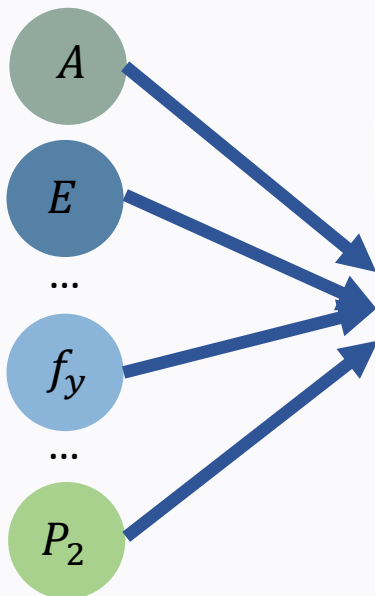


Global Sensitivity Analysis

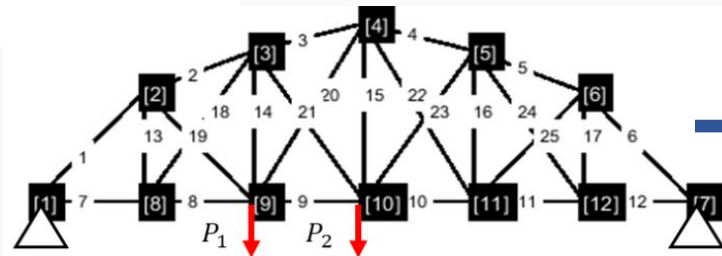
Motivation

- Consider a numerical model of a structure

Inputs



Model



Output

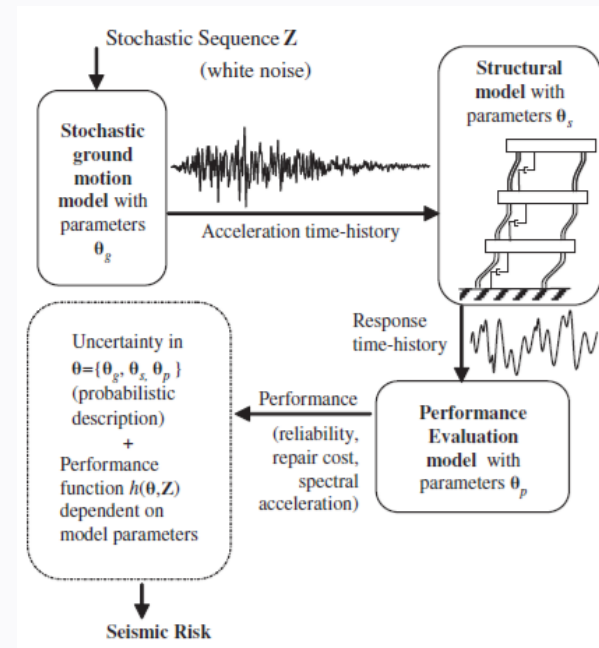
midspan displacement

Failure index (0,1)

- Will all the input parameters contribute to the response?
- Which input factors are more influential than others?

Applications of GSA

- **To gain insights**
 - How different parameters and their interactions affect a system



The parameters related to **the local site diminution effect (...)** can be **in general neglected**; (...) **temporal envelope function parameters** have a **considerable contribution** towards the total risk only for lower moment magnitudes, especially (...)
(Vetter & Taflanidis, 2011)

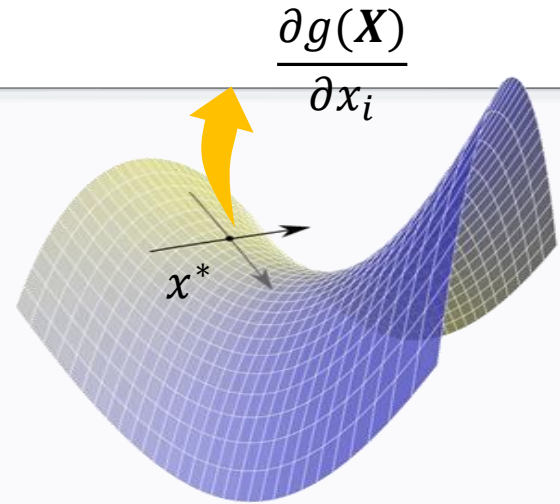
Applications of GSA

- **To gain insights**
 - How different parameters and their interactions affect a system
- **Dimensionality reduction**
 - By identifying uninfluential (redundant) factors
- **Informed decision making**
 - To find parameters for which new data acquisition reduces target uncertainty the most
 - To identify most effective decision options
- **Model diagnostics**
 - After developing a model, one may compare GSA results with expert knowledge

Local Sensitivity Analysis

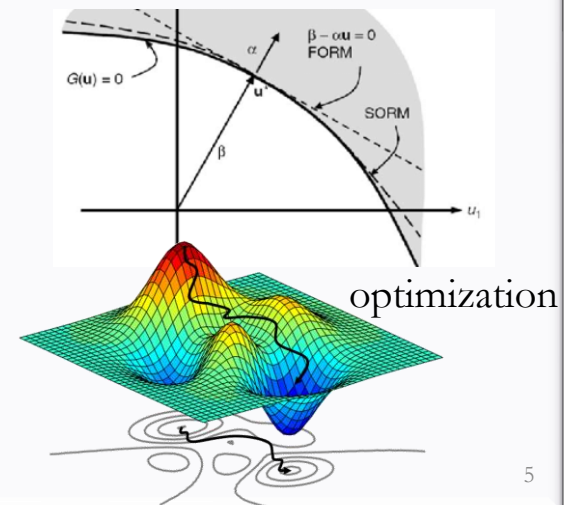
- Rate of change (slope)

$$S_i^D(\mathbf{X}) = \frac{\partial g(\mathbf{X})}{\partial X_i}$$



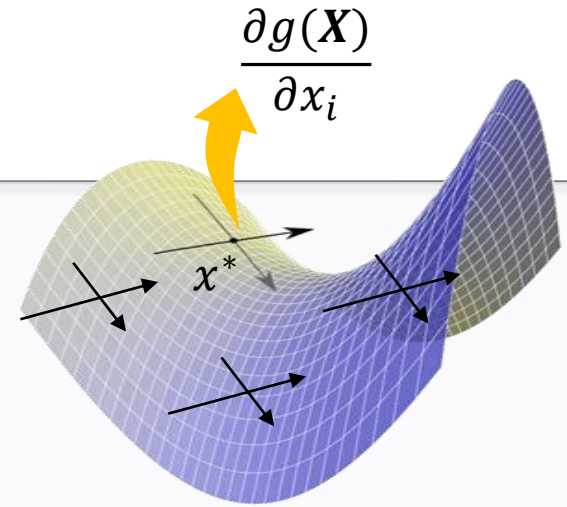
- Studies the impact of small perturbations on the model outputs
- Evaluated at a reference point \mathbf{X}
- One-factor-at-a-time evaluation
- Used in reliability analysis / optimization

e.g. structural reliability analysis



Local Sensitivity Analysis

- How to explore entire variability space?



Is the average of gradients
a good measure?

- Consider an example

$$Y = g(X_1, X_2) = 2X_1 + X_2$$

$$X_1 \sim N(0, 0.5^2), X_2 \sim N(0, 5^2)$$

Among X_1 and X_2 , which variable is more “important”?

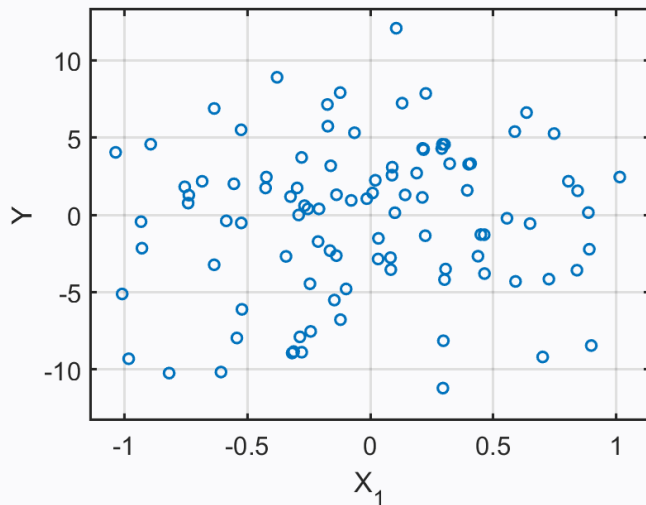
Local Sensitivity Analysis

$$Y = g(X_1, X_2) = 2X_1 + X_2$$

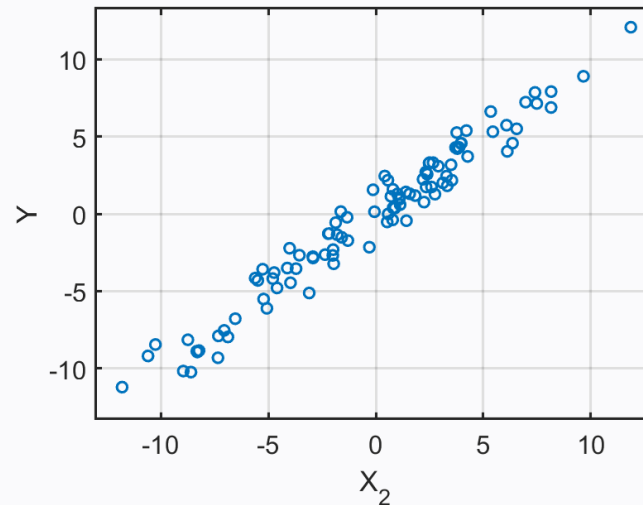
$$X_1 \sim N(0, 0.5^2), \quad X_2 \sim N(0, 5^2)$$

- If we decide the importance by ‘partial derivative’ measure, X_1 is important
- But if we inspect the scatter plots,

X_2 seem to dominate the response



Y vs. X_1



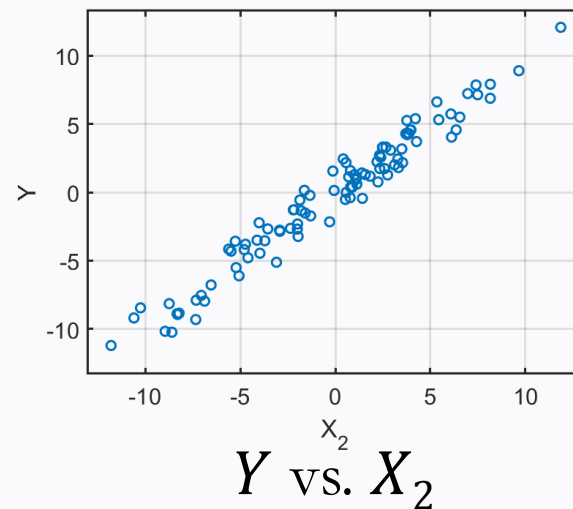
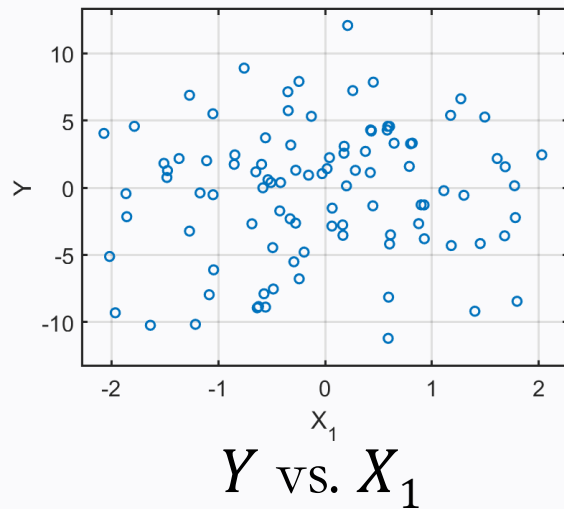
Y vs. X_2

Local Sensitivity Analysis

- Sigma-normalized derivative

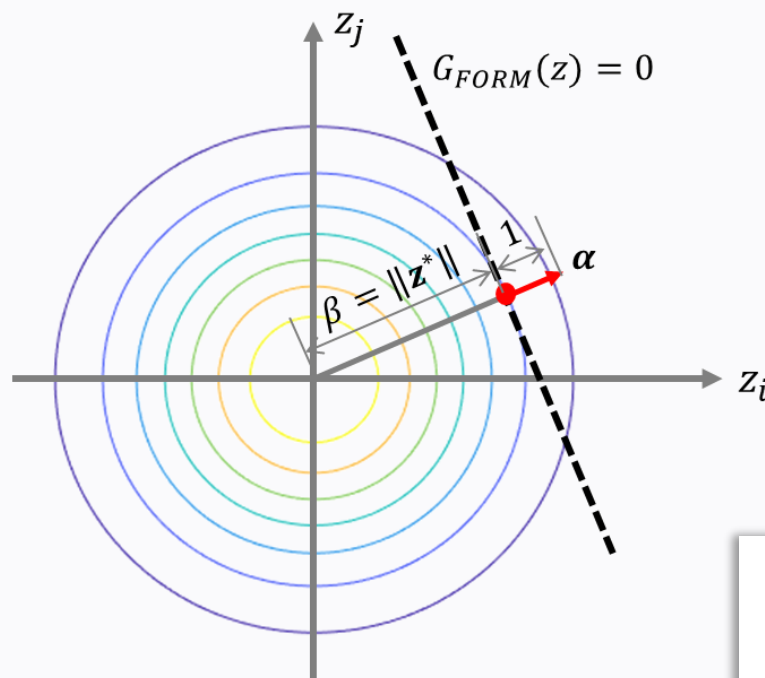
$$S_i^{SD}(\mathbf{X}) = \frac{\sigma_{X_i}}{\sigma_Y} \frac{\partial g(\mathbf{X})}{\partial X_i}$$

X_2 is five times more important than X_1



Local Sensitivity Analysis

- ‘Partial derivative’ in the standard random variable domain
 - When the random variables are **independent**, each variable can be transformed to the standard normal variable, $Z_i = T(X_i)$.
 - Example: FORM analysis



Importance vector:
normalized gradient

$$\alpha = - \frac{\nabla G(\mathbf{z}^*)}{\|\nabla G(\mathbf{z}^*)\|}$$

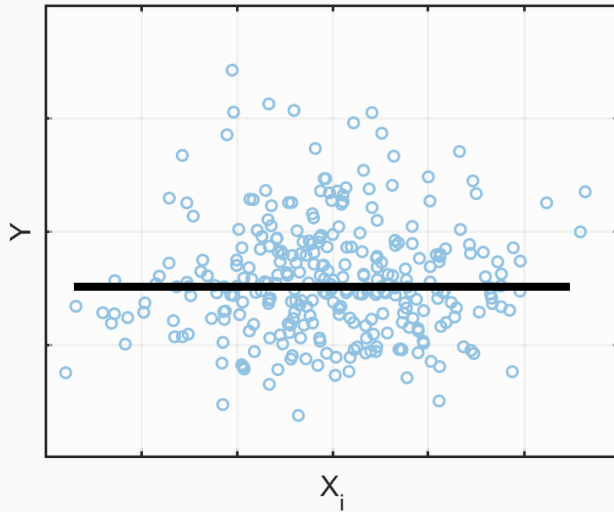
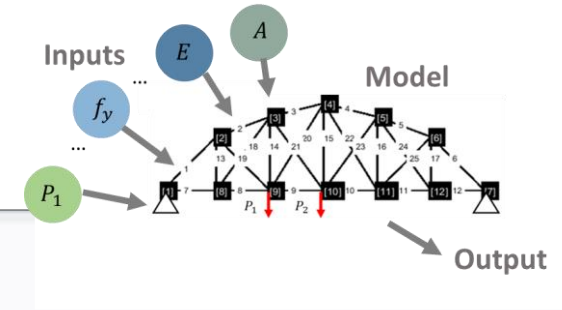
Note

$$\alpha = - \frac{\mathbf{z}^*}{\beta}$$

$Z_1 = F_Z^{-1}(F_{X_1}(X_1))$	For dependent
$Z_2 = F_Z^{-1}(F_{X_2 X_1}(X_2 X_1))$	variables
\vdots	
$Z_n = F_Z^{-1}(F_{X_n X_{n-1}, \dots, X_1}(X_n X_{n-1}, \dots, X_1))$	

Variance-based Sensitivity

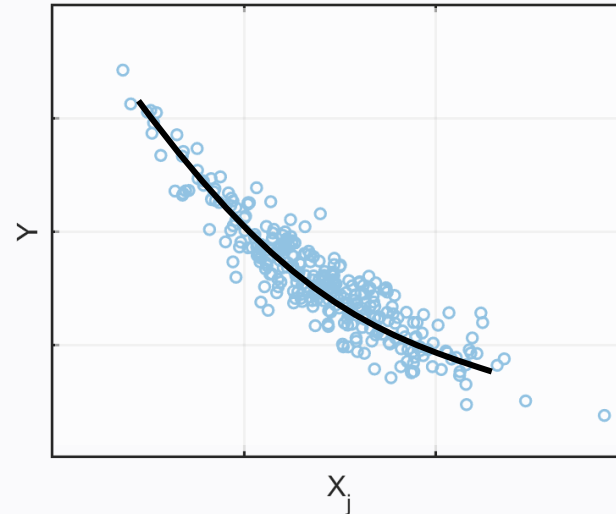
- Intuition behind the Sobol indices



$\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|\mathbf{x}_i]$ is almost constant throughout different \mathbf{x}_i values

➔ $\text{Var}_{x_i}[\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|\mathbf{x}_i]]$ is almost zero

➔ Low sensitivity



$\mathbb{E}_{\mathbf{x}_{\bar{j}}}[Y|\mathbf{x}_j]$ depends on \mathbf{x}_j

➔ $\text{Var}_{x_j}[\mathbb{E}_{\mathbf{x}_{\bar{j}}}[Y|\mathbf{x}_j]]$ is larger

➔ High sensitivity

Variance Decomposition

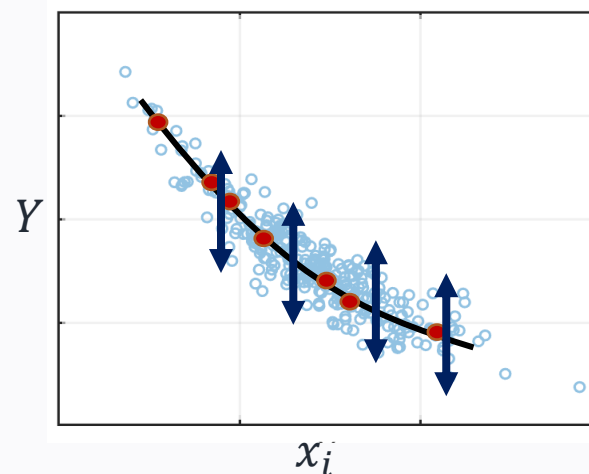
- $\text{Var}_{x_i} [\mathbb{E}_{x_{\bar{i}}} [Y|x_i]]$ is a measure of sensitivity
- The Law of Total Variance

$$\text{Var}[Y] = \text{Var}_{x_i} [\mathbb{E}_{x_{\bar{i}}} [Y|x_i]] + \mathbb{E}_{x_i} [\text{Var}_{x_{\bar{i}}} [Y|x_i]]$$

Explained by x_i

Not explained by x_i

i.e. the expected reduction in variance that would be obtained if x_i could be fixed



Variance Decomposition

- $\text{Var}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]$ is a measure of sensitivity
- The Law of Total Variance

$$\text{Var}[Y] = \text{Var}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right] + \mathbb{E}_{x_i} \left[\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]$$

- Derivation

$$\begin{aligned} \text{Var}[Y] &= \mathbb{E}[Y^2] - \mathbb{E}[Y]^2 \\ &= \mathbb{E}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y^2|x_i] \right] - \mathbb{E}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]^2 \\ &= \mathbb{E}_{x_i} \left[\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i] + \mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i]^2 \right] - \mathbb{E}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]^2 \\ &= \mathbb{E}_{x_i} \left[\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right] + \mathbb{E}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i]^2 \right] - \mathbb{E}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]^2 \\ &= \mathbb{E}_{x_i} \left[\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right] + \text{Var}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right] \end{aligned}$$

Variance Decomposition

- $\text{Var}_{x_i} [\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i]]$ is a measure of sensitivity
- The Law of Total Variance

$$\text{Var}[Y] = \text{Var}_{x_i} [\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i]] + \mathbb{E}_{x_i} [\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i]]$$



$$1 = \frac{\text{Var}_{x_i} [\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i]]}{\text{Var}[Y]} + \frac{\mathbb{E}_{x_i} [\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i]]}{\text{Var}[Y]}$$

Always greater than 0

Sensitivity index

In range of [0,1]

Variance Decomposition

- The Law of Total Variance

$$1 = \frac{\text{Var}_{x_i} \left[\mathbb{E}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]}{\text{Var}[Y]} + \frac{\mathbb{E}_{x_i} \left[\text{Var}_{\mathbf{x}_{\bar{i}}} [Y|x_i] \right]}{\text{Var}[Y]}$$

- Sobol Sensitivity Index

$$S_i = \frac{\text{Var}[\mathbb{E}[Y|x_i]]}{\text{Var}[Y]}$$

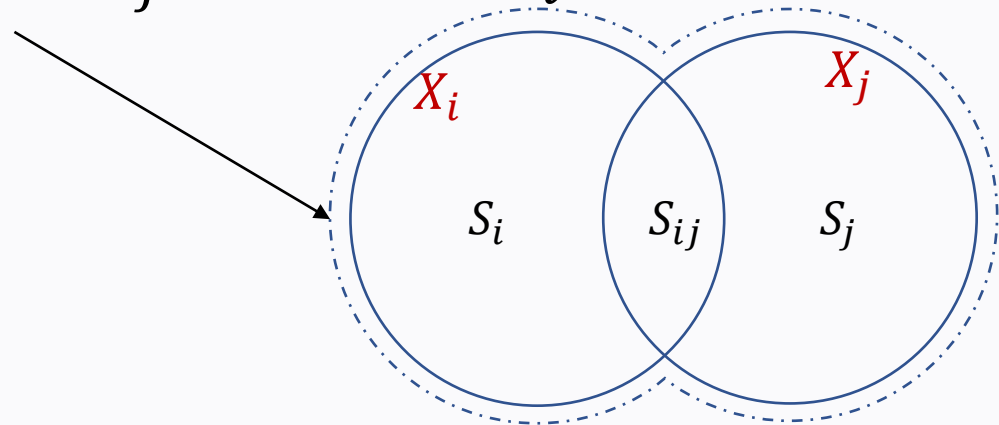
$$S_i = 1 - \frac{\mathbb{E}[\text{Var}[Y|x_i]]}{\text{Var}[Y]}$$

- Main-effect index, First-order index

Second-order Sensitivity Measures

$$S_{ij} = \frac{\text{Var}_{x_i x_j} \left[\mathbb{E}_{\mathbf{x}_{\bar{ij}}} [Y | X_i, X_j] \right]}{\text{Var}[Y]} - S_i - S_j$$

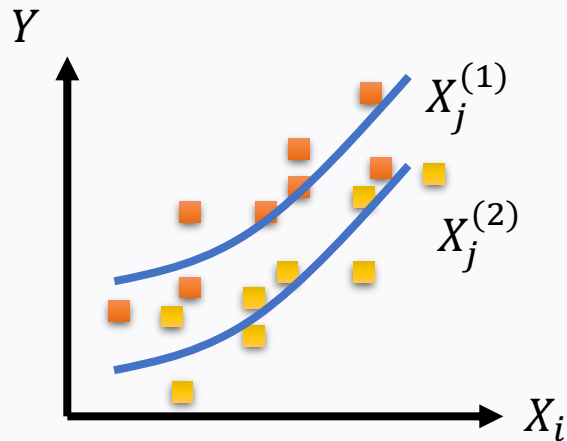
joint contribution of X_i and X_j contribution of X_i contribution of X_j



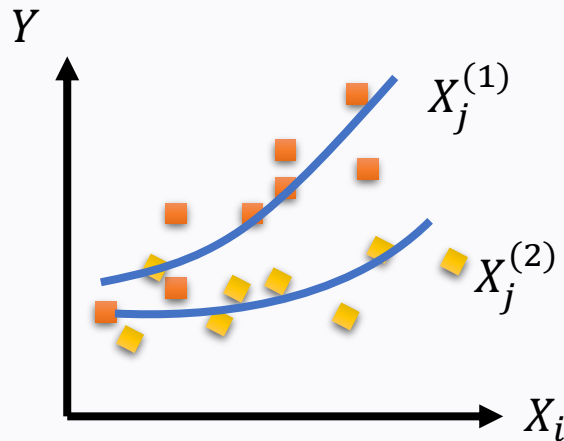
S_{ij} captures the pure interaction effect

Interaction Effect

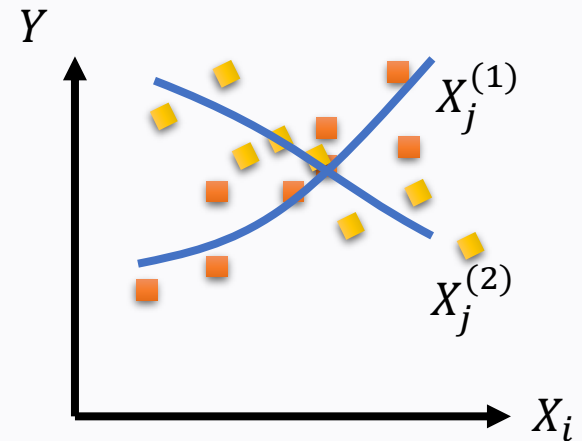
- Interaction effect: X_i vs. Y is affected by X_j



No interaction
 $S_{ij} = 0$



Interaction between X_i and X_j
 $S_{ij} > 0$



- Nonadditive terms create the interaction

$$g_A(X_1, X_2) = 3X_1^3 + \log(X_2)$$

$$g_B(X_1, X_2) = 3X_1^3 + \log(X_2) + X_1X_2$$

No interaction $S_{12} = 0$

Interaction between X_1 and X_2

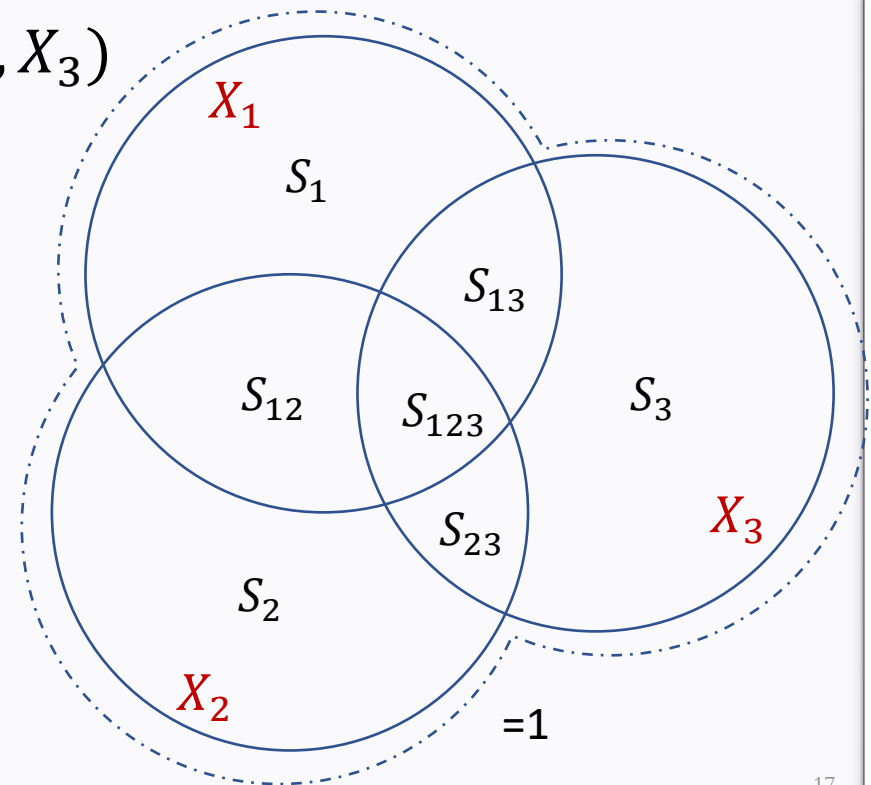
$$S_{12} > 0$$

Higher-order Sensitivity Indices

When random variables are independent below holds

$$1 = \sum_i S_i + \sum_{i < j} S_{ij} + \dots + S_{1,2,\dots,d}$$

Consider an example $Y = g(X_1, X_2, X_3)$



Total-effect Index

$$S_i^T = 1 - \frac{\text{Var}_{\mathbf{X}_{\bar{i}}} \left[\mathbb{E}_{x_i} [Y | \mathbf{X}_{\bar{i}}] \right]}{\text{Var}[Y]}$$

Conditioning on all
variables but X_i

S_i^T accounts for all the interaction effects associated with a variable X_i

Total-effect Index

- For example, consider a function

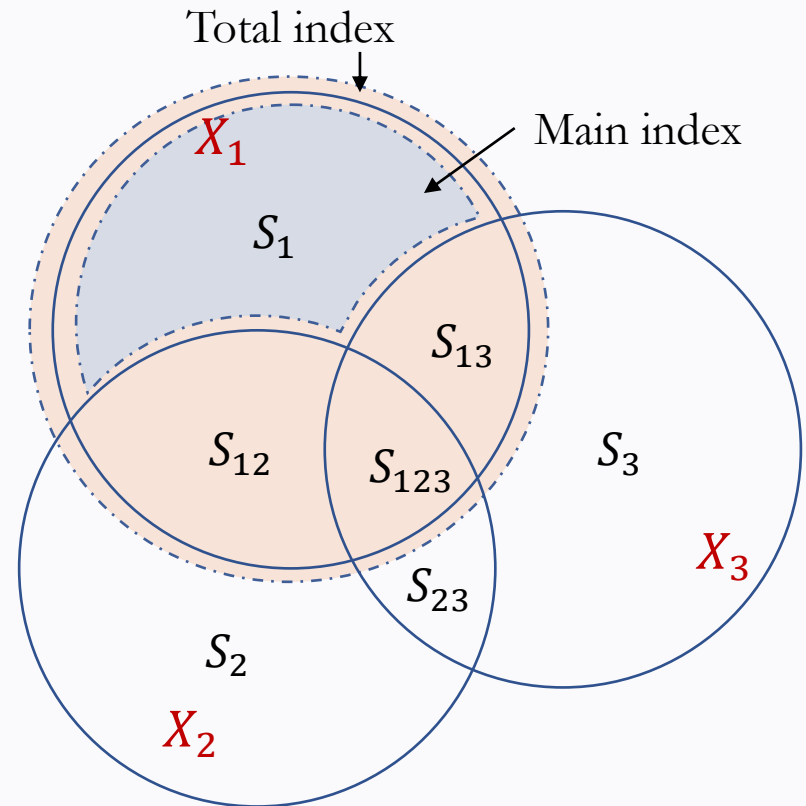
$$Y = g(X_1, X_2, X_3)$$

Total-effect index for X_1 is

$$S_1^T = 1 - S_{23} - S_2 - S_3$$

When the variables are independent

$$S_1^T = S_1 + S_{12} + S_{13} + S_{123}$$



Analysis of Variance (ANOVA) Decomposition

Consider uncorrelated \mathbf{X} distributed within a unit hyper-cube

$$Y = g(\mathbf{X})$$

The function can be expanded as

$$Y = g_0 + \sum_i g_i(X_i) + \sum_{i < j} g_{ij}(X_i, X_j) + g_{12, \dots, d}(X_1, X_2, \dots, X_d)$$

This formula is called ANOVA representation if

$$\int_0^1 g_{\mathbf{u}}(\mathbf{X}_{\mathbf{u}}) dx_k = 0, \quad k \in \mathbf{u}$$

for any $\mathbf{u} \subseteq \{1, 2, \dots, d\}$. For example,

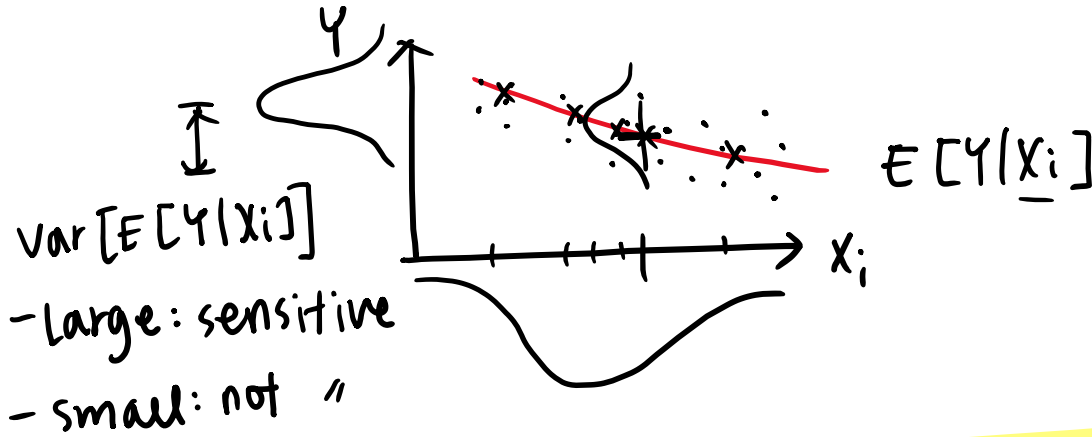
$$\int_0^1 g_{ij}(X_i, X_j) dX_i = 0 \quad \text{and} \quad \int_0^1 g_{ij}(X_i, X_j) dX_j = 0$$

Review

1) main sobol index

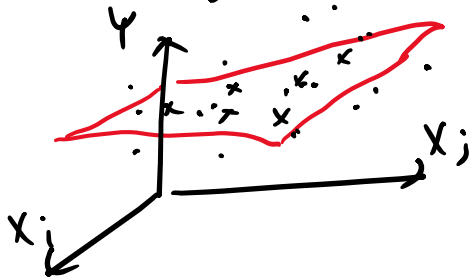
$$S_i = \frac{\text{Var}[E[Y|X_i]]}{\text{Var}[Y]}$$

$$S_i \leq S_i^T$$



2) higher order sobol index

$$S_{ij} = \frac{\text{Var}[E[Y|X_i, X_j]]}{\text{Var}[Y]} - S_i - S_j$$



includes 'effect' of
 X_i, X_j , interaction
 b/w X_i, X_j

3) total sobol index

$$S_i^T = 1 - \frac{\text{Var}[E[Y|\underline{X}_{\sim i}]]}{\text{Var}[Y]}$$

e.g. when $d=3$

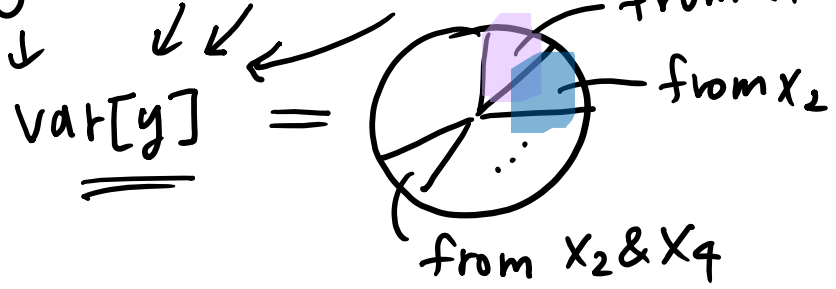
$$S_2^T = S_2 + S_{12} + S_{23} + S_{123}$$

ANOVA - derivation

assump.

$X \sim \text{uniform}(0,1), \text{ ind.}$

$$y = f(x_1, x_2, \dots, x_d)$$



$$Y = g(x_1, x_2, \dots, x_d)$$

$$= g_0 + \sum_i g_i(x_i) + \sum_{i < j} g_{ij}(x_i, x_j) + \dots + g_{12\dots d}(x_1, \dots, x_d)$$

given orthogonality \hookrightarrow is unique - "ANOVA".

e.g. $\int_0^1 g_{235}(x_2, x_3, x_5) dx_2 = 0$

$$\int_0^1 g_{235}(x_2, x_3, x_5) dx_3 = 0$$

" $dx_5 = 0$

$$S_i = \frac{V_i}{V}$$

Sensitivity

$$\text{Var}[Y] = V = \sum_i V_i + \underbrace{\sum_{i < j} V_{ij} + \dots + V_{12\dots d}}_{\text{interaction}}$$

\uparrow Variance fraction coming from X_i

\rightarrow 50% X_1
 \rightarrow 40% X_2
 \rightarrow 10% $X_1 \& X_2$

Because of orthogonality

$$E[Y] = \mu_0$$

$$E[Y|X_i] = \mu_0 + \mu_i(X_i)$$

$$E[Y|X_i, X_j] = \mu_0 + \mu_i(X_i) + \mu_j(X_j) + \mu_{ij}(X_i, X_j)$$

↳

$$\mu_i(X_i) = E[Y|X_i] - \mu_0$$

$$\mu_{ij}(X_i, X_j) = E[Y|X_i, X_j] - E[Y|X_i] - E[Y|X_j] + \mu_0$$

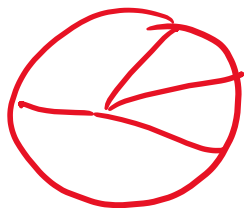
↳

$$\frac{\text{Var}[\mu_i(X_i)]}{\text{Var}[Y]} = \frac{V_i}{V} = \frac{\text{Var}[E[Y|X_i]]}{\text{Var}[Y]} = S_i$$

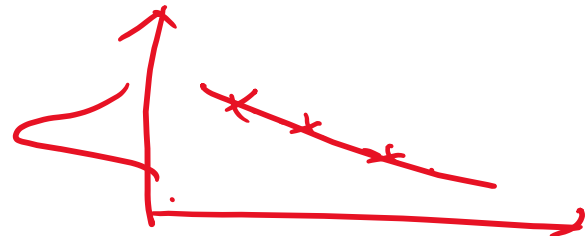
(when X independent)

Law of total var

ANOVA



decomposition
of total
var:



Analysis of Variance (ANOVA) Decomposition

$$Y = g_0 + \sum_i g_i(X_i) + \sum_{i < j} g_{ij}(X_i, X_j) + g_{12,\dots,d}(X_1, X_2, \dots, X_d)$$

Taking $\text{Var}[\cdot]$ on both sides

$$\text{Var}[Y] = V = \sum_i V_i + \sum_{i < j} V_{ij} + \dots + V_{12\dots d}$$

The proportion of variance attributed to X_i

$$1 = \sum_i \frac{V_i}{V} + \sum_{i < j} \frac{V_{ij}}{V} + \dots + \frac{V_{12\dots d}}{V}$$

Equivalent to Sobol index why?

Analysis of Variance (ANOVA) Decomposition

$$Y = g_0 + \sum_i g_i(X_i) + \sum_{i < j} g_{ij}(X_i, X_j) + g_{12, \dots, d}(X_1, X_2, \dots, X_d)$$

$$= 0$$

$\mathbb{E}[\cdot]$ on both sides, i.e. integrate over \mathbf{X}

$$\mathbb{E}[Y] = g_0$$

$\mathbb{E}[\cdot | \mathbf{X}_{\mathbf{u}}]$ on both sides, i.e. integrate over all but $\mathbf{u} \subseteq \{1, 2, \dots, d\}$

$$\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y | X_i] = g_0 + g_i(X_i)$$

$$\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y | X_i, X_j] = g_0 + g_i(X_i) + g_j(X_j) + g_{ij}(X_i, X_j)$$

....

Analysis of Variance (ANOVA) Decomposition

$$\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|X_i] = g_0 + g_i(X_i)$$

$$\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|X_i, X_j] = g_0 + g_i(X_i) + g_j(X_j) + g_{ij}(X_i, X_j)$$

....



$$\text{Var}_{x_i}[\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|X_i]] = V_i$$

$$\text{Var}_{x_i}[\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|X_i, X_j]] = V_i + V_j + V_{ij}$$

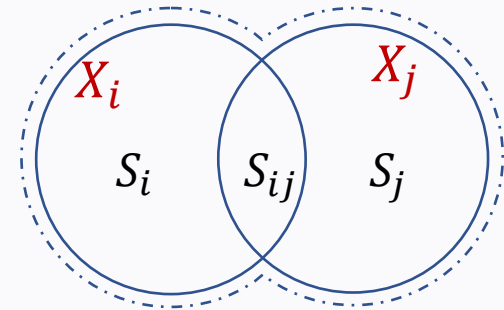
....



$$\frac{\text{Var}_{x_i}[\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|X_i]]}{\text{Var}[Y]} = \frac{V_i}{V} = S_i$$

$$\frac{\text{Var}_{x_i}[\mathbb{E}_{\mathbf{x}_{\bar{i}}}[Y|X_i, X_j]]}{\text{Var}[Y]} = \frac{V_i}{V} + \frac{V_j}{V} + \frac{V_{ij}}{V} = S_i + S_j + S_{ij}$$

....



ANOVA vs. The Law of Total Variance

Consider X_1 ,

The Law of Total Variance

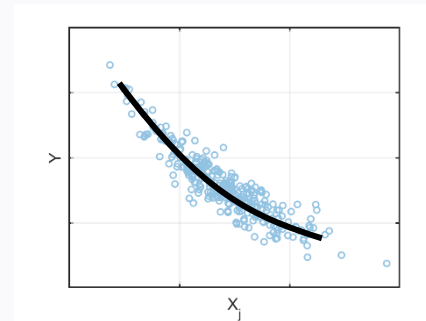
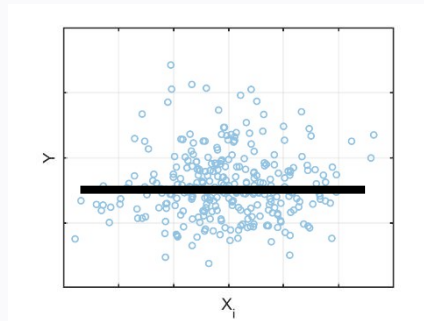
$$\text{Var}[Y] = \underbrace{\text{Var}_{x_i} \left[\mathbb{E}_{x_i} [Y|X_1] \right]}_{\text{ANOVA}} + \underbrace{\mathbb{E}_{x_i} \left[\text{Var}_{x_i} [Y|X_1] \right]}_{\text{The Law of Total Variance}}$$

ANOVA

$$\begin{aligned} \text{Var}[Y] &= V_1 + \underbrace{\sum_{i=2}^d V_i}_{\text{ANOVA}} + \underbrace{\sum_{i < j} V_{ij} + \dots + V_{12\dots d}}_{\text{The Law of Total Variance}} \\ &= \text{Var}_{x_i} \left[\mathbb{E}_{x_i} [Y|X_1] \right] \end{aligned}$$

Remarks

- When variables are correlated
 - The Law of Total Variance does not require the assumption of independence
 - Intuitive interpretation still holds

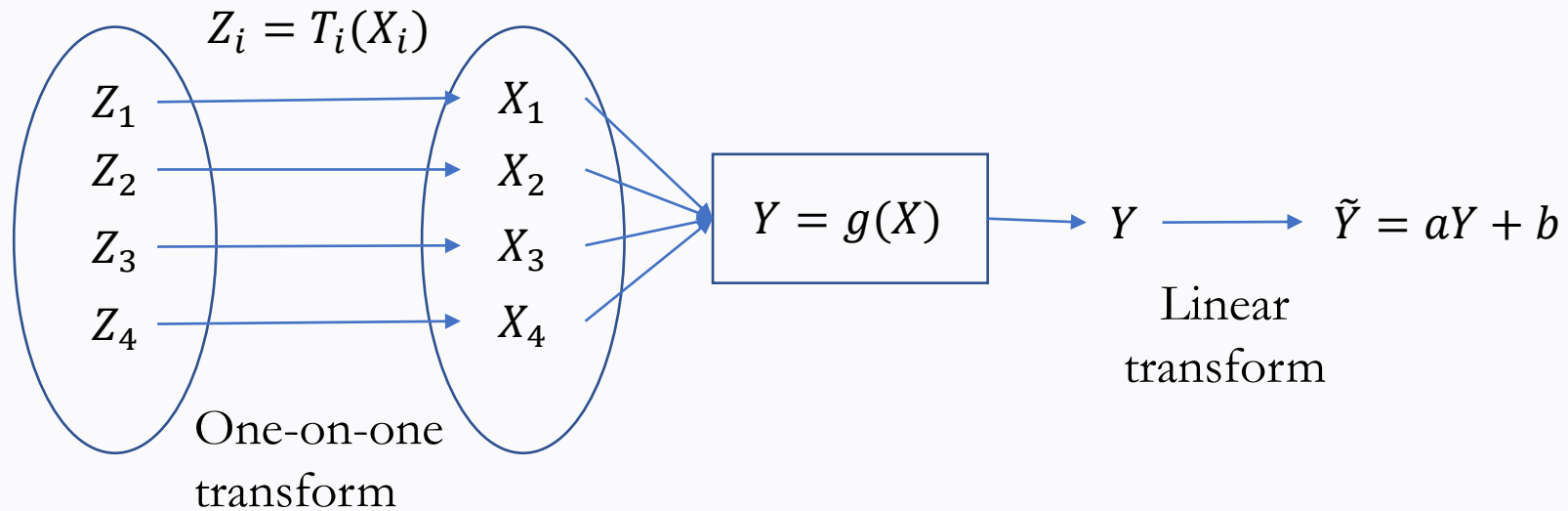


- ANOVA requires the assumption of independence

$$1 > \sum_i S_i + \sum_{i < j} S_{ij} + \dots + S_{1,2,\dots,d}$$

Remarks

- When \mathbf{X} are independent random variables, the sensitivity indices are invariant to any one-on-one transformation of **input** $Z_i = T_i(X_i)$



- The sensitivity indices are invariant to the linear transform of **output**

Example FORM limit state function

$$Y = G_{\text{FORM}}(\underline{z}) = \nabla G(\underline{z}^*) \cdot (\underline{z} - \underline{z}^*)$$

$$\frac{\text{Var}[E[Y|X]]}{\text{Var}[Y]} = \frac{\frac{\partial G}{\partial z_1}(\underline{z}^*) \cdot (z_1 - z_1^*) + \frac{\partial G}{\partial z_2}(\underline{z}^*) \cdot (z_2 - z_2^*) + \dots + \frac{\partial G}{\partial z_d}(\underline{z}^*) \cdot (z_d - z_d^*)}{\dots}$$

$$\text{Var}[Y] = \left(\frac{\partial G}{\partial z_1}(\underline{z}^*)\right)^2 + \left(\frac{\partial G}{\partial z_2}(\underline{z}^*)\right)^2 + \dots + \left(\frac{\partial G}{\partial z_d}(\underline{z}^*)\right)^2 \quad z_i \sim N(0,1) \text{ ind.}$$

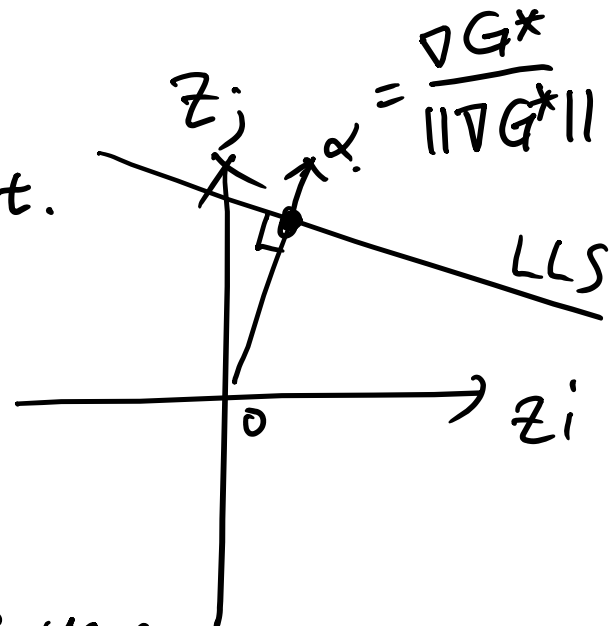
$$= \|\nabla G^*\|^2$$

$$E[Y|z_1] = \frac{\partial G}{\partial z_1}(\underline{z}^*) \cdot z_1 + \text{const.}$$

$$\text{Var}_{z_1}[E[Y|z_1]] = \left(\frac{\partial G}{\partial z_1}(\underline{z}^*)\right)^2$$

$$s_i = \frac{\left|\frac{\partial G}{\partial z_i}(\underline{z}^*)\right|^2}{\|\nabla G^*\|^2} = \alpha_i^2$$

← Importance vector.



Special case – Linear model $g(\mathbf{x})$

- For a linear model, below are equivalent
 - Sigma-normalized derivative
 - Linear regression coefficients
 - Variance-based sensitivity indices
- Example – FORM limit state surface

$$G_{FORM}(\mathbf{z}) = \nabla G(\mathbf{z}^*)(\mathbf{z} - \mathbf{z}^*)$$

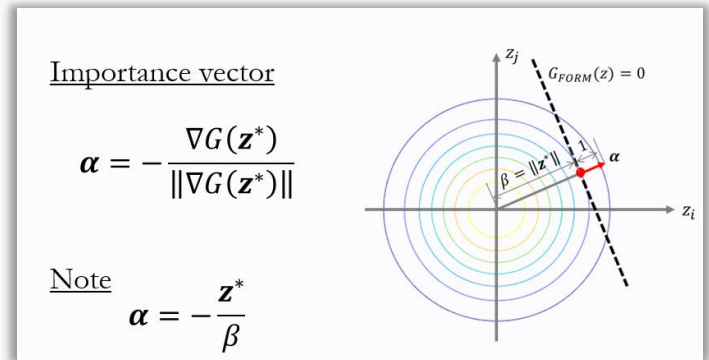
$$= \frac{\partial G(\mathbf{z}^*)}{\partial z_1} (z_1 - z_1^*) + \dots + \frac{\partial G(\mathbf{z}^*)}{\partial z_d} (z_d - z_d^*)$$

$$\text{Var}[Y_{FORM}] = \|\nabla G(\mathbf{z}^*)\|^2$$

$$\mathbb{E}[Y_{FORM}|z_i] = \frac{\partial G(\mathbf{z}^*)}{\partial z_i} z_i$$

$$\text{Var}[\mathbb{E}[Y_{FORM}|z_i]] = \left(\frac{\partial G(\mathbf{z}^*)}{\partial z_i}\right)^2$$

$$S_i = \frac{\text{Var}[\mathbb{E}[Y_{FORM}|z_i]]}{\text{Var}[Y_{FORM}]} = \alpha^2$$

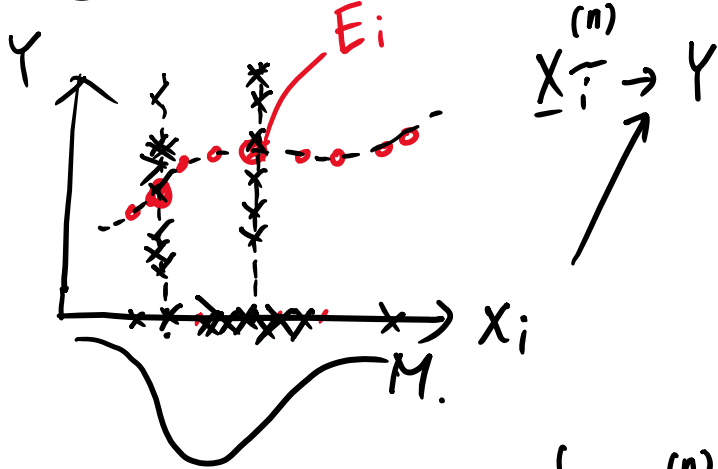


Algorithms GSA.

$$S_i = \frac{\text{Var}[E[Y|X]]}{\text{Var}[Y]} \leftarrow \text{Numerator}$$

① MCS

Samples of E_i



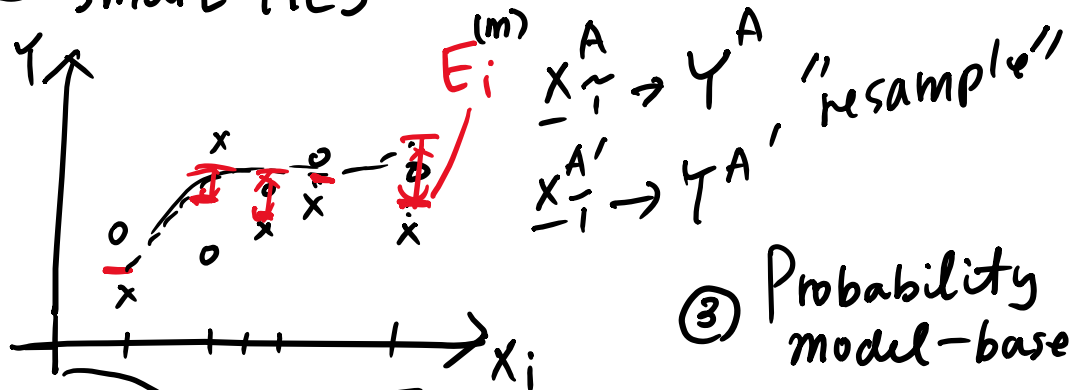
$$E[Y|x] \approx E_i = \frac{1}{N} \sum Y^{(n)}$$

$\text{Var}[E[Y|x]] \approx$ sample var. of E_i

$$= \frac{1}{M} \sum_{m=1}^M (E_i - \bar{E}_i)^2$$

$\Rightarrow N \times M \times d \times 2$

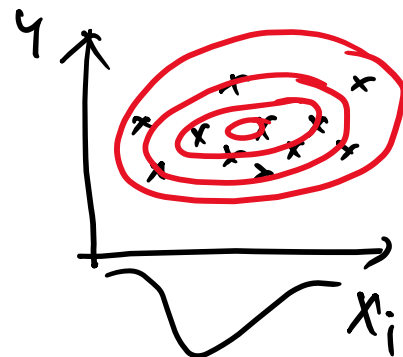
② smart MCS



$$\text{Var}[E[Y|x]]$$

\approx sample var of $E_i^{(m)}$

③ Probability model-based



fitting joint PDF of x_i, y

$$f(y|x_i)$$

$$= \frac{f(x_i, y)}{f(x_i)}$$

$$\Rightarrow f(x_i, y)^2$$

Algorithms: (1) Monte Carlo Estimation

Requires two-fold integration for “variance” and “mean” operation

$$S_i = \frac{\text{Var}_{x_i} \left[\mathbb{E}_{x_{\bar{i}}} [Y | x_i] \right]}{\text{Var}[Y]}$$

```
For n=1:N
```

```
  sample  $x_i^{(n)}$ 
```

```
    For m=1:N
```

```
      sample  $x_{\bar{i}}^{(m)}$ 
```

```
      simulate  $y^{(m,n)} = g(x_i^{(n)}, x_{\bar{i}}^{(m)})$ 
```

```
    end
```

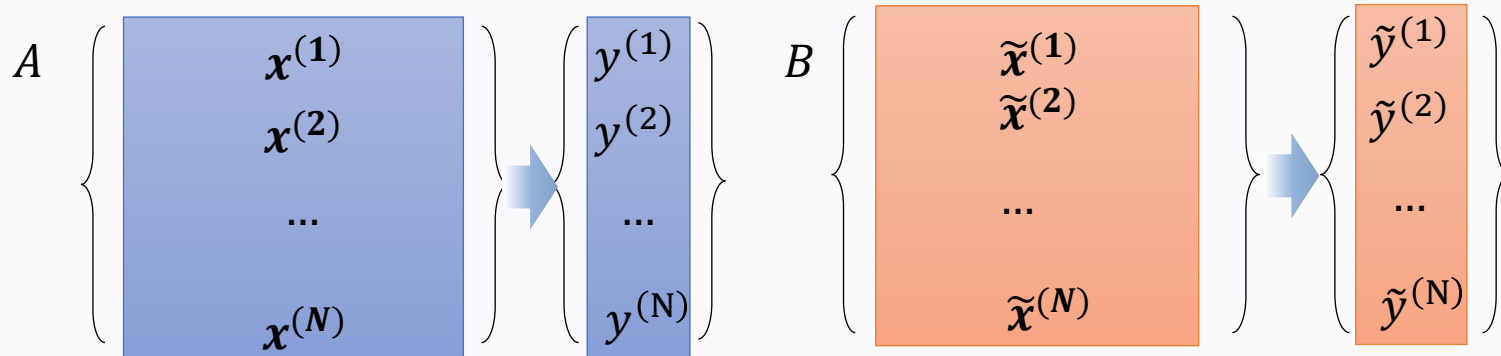
```
end
```

$$E^{(n)} = \mathbb{E}_{x_{\bar{i}}} [Y | x_i^{(n)}] \approx \frac{1}{N} \sum_{m=1}^N y^{(m,n)}$$

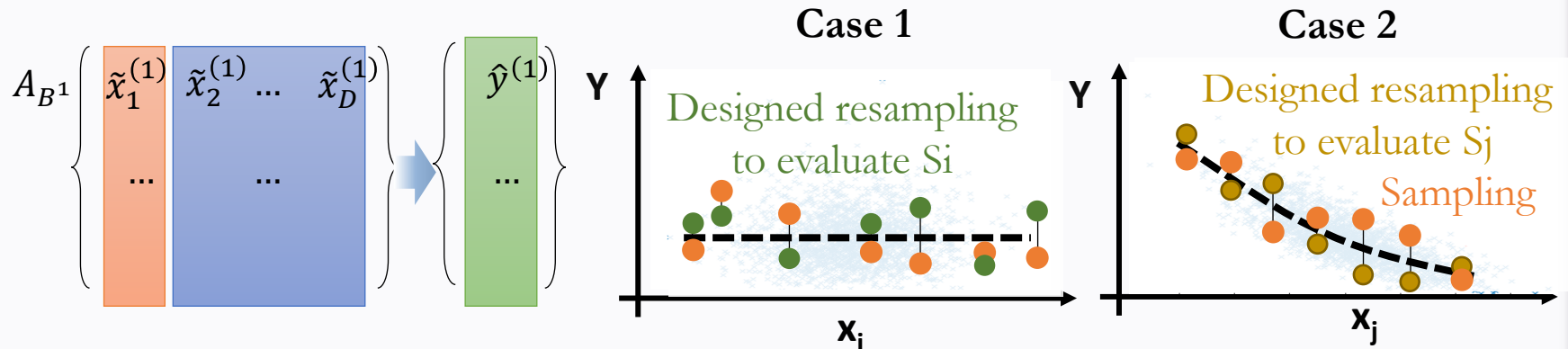
$$\text{Var}_{x_i} \left[\mathbb{E}_{x_{\bar{i}}} [Y | x_i] \right] \approx \text{sample variance of } E^{(n)}$$

Algorithms: (2) Smart Monte Carlo

- Start with two random N sample set



- Designed sample set to estimate Sobol indices of X_1



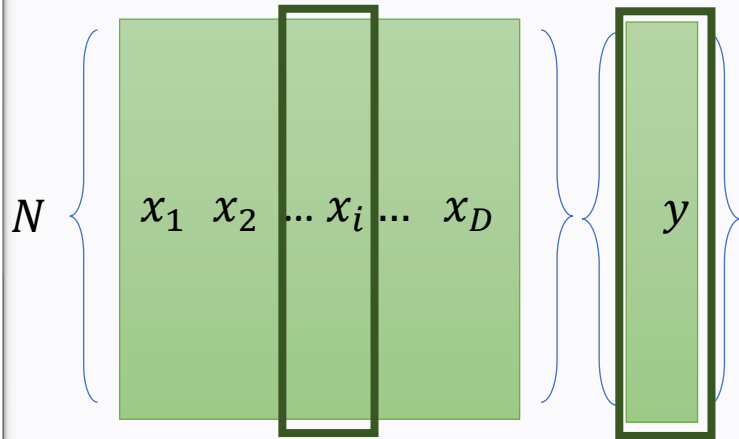
Algorithms: (2) Smart Monte Carlo

Saltelli, 2009

$V_{X_i}(E_{\mathbf{X}_{\sim i}}(Y X_i))$ for S_i	Reference
(a) $\frac{1}{N} \sum_{j=1}^N f(\mathbf{A})_j f(\mathbf{B}_A^{(i)})_j - f_0^2$	'Sobol' 1993' [37]
(b) $\frac{1}{N} \sum_{j=1}^N f(\mathbf{B})_j (f(\mathbf{A}_B^{(i)})_j - f(\mathbf{A})_j)$	[this paper]
(c) $V(Y) - \frac{1}{2N} \sum_{j=1}^N (f(\mathbf{B})_j - f(\mathbf{A}_B^{(i)})_j)^2$	'Jansen 1999' [14]
$E_{\mathbf{X}_{\sim i}}(V_{X_i}(Y \mathbf{X}_{\sim i}))$ for S_{Ti}	
(d) $V(Y) - \frac{1}{N} \sum_{j=1}^N f(\mathbf{A})_j f(\mathbf{A}_B^{(i)})_j + f_0^2$	'Homma 1996' [11]
(e) $\frac{1}{N} \sum_{j=1}^N f(\mathbf{A})_j (f(\mathbf{A})_j - f(\mathbf{A}_B^{(i)})_j)$	'Sobol' 2007' [39]
(f) $\frac{1}{2N} \sum_{j=1}^N (f(\mathbf{A})_j - f(\mathbf{A}_B^{(i)})_j)^2$	'Jansen 1999' [14] and [this paper]

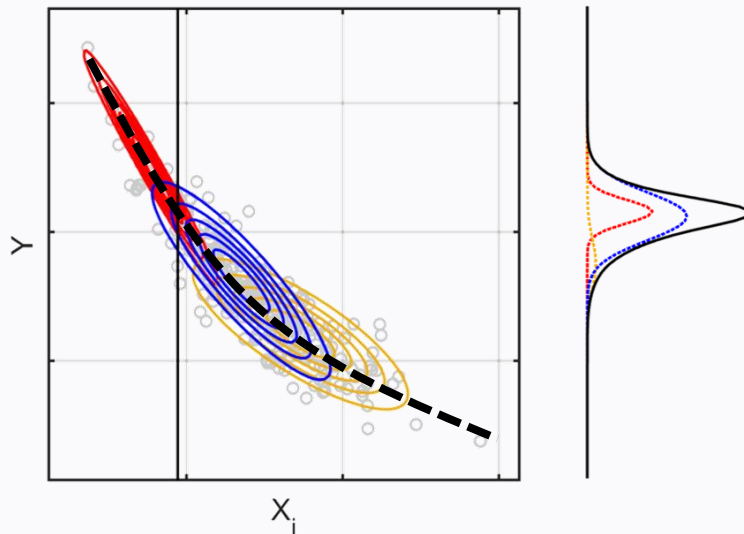
Algorithms: (3) Probability model-based GSA

- N -MCS samples are required - existing samples can be used!



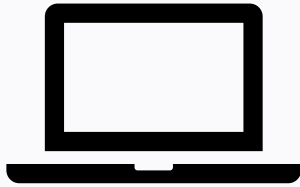
Estimation algorithm

- Approximate joint distribution of $f(X_i, Y)$ using a Gaussian mixture model (GMM)
- Estimate $\mathbb{E}[Y|X_i]$ from GMM $f(X_i, Y)$
- Repeat for different $X_i^{(n)}$ samples to get sample variance



$$\text{Var}_{x_i} \left[\mathbb{E}_{x_i} \left[Y | X_i^{(n)} \right] \right]$$

For Thursday class (4/21)



Bring laptop



Download
quoFEM

DESIGNSAFE

Register for a
DesignSafe Account

- quoFEM: <https://simcenter.designsafe-ci.org/research-tools/quofem-application/>
- DesignSafe: <https://www.designsafe-ci.org/account/register/>

Variance-based Reliability Sensitivity Analysis

- Reliability-oriented sensitivity analysis
- Quantity of interest:

$$q = \mathbb{1}(G(\mathbf{X})) = \begin{cases} 1 & G(\mathbf{X}) \leq 0 \\ 0 & G(\mathbf{X}) > 0 \end{cases}$$



Bernoulli

$$P(q=1) = P_f$$
$$P(q=0) = 1 - P_f$$

Variance [\[edit\]](#)

The **variance** of a Bernoulli distributed X is

$$\text{Var}[X] = pq = p(1 - p)$$

- $E[q] = E[\mathbb{1}(G(\mathbf{X}))] = P_f$
- $\text{Var}[q] = \text{Var}[\mathbb{1}(G(\mathbf{X}))] = P_f(1 - P_f)$

Reformulation of Sobol index

- Main Sobol index

$$S_i = \frac{\text{Var}_{X_i} \left[\mathbb{E}_{X_{\bar{i}}} [q|X_i] \right]}{\text{Var}[q]} = \frac{\text{Var}_{X_i} \left[\mathbb{E}_{X_{\bar{i}}} [q|X_i] \right]}{P_f(1 - P_f)}$$

- Similarly,

$$\mathbb{E}_{X_{\bar{i}}} [q|X_i] = P_{f|X_i}$$

$$\begin{aligned} \text{Var}_{X_i} \left[\mathbb{E}_{X_{\bar{i}}} [q|X_i] \right] &= \text{Var}_{X_i} [P_{f|X_i}] \\ &= \mathbb{E}_{X_i} [P_{f|X_i}^2] - \mathbb{E}_{X_i} \left[\mathbb{E}_{X_{\bar{i}}} [P_{f|X_i}] \right]^2 \\ &= \mathbb{E}_{X_i} [P_{f|X_i}^2] - P_f^2 \end{aligned}$$

$$S_i = \frac{\text{Var}_{X_i} \left[\mathbb{E}_{X_{\bar{i}}} [q|X_i] \right]}{P_f(1 - P_f)} = \frac{\mathbb{E}_{X_i} [P_{f|X_i}^2] - P_f^2}{P_f(1 - P_f)}$$

Reformulation of Sobol index

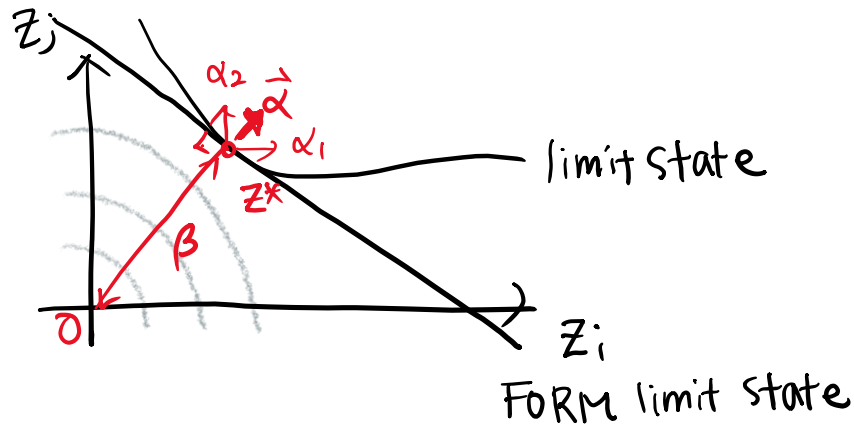
$$S_i = \frac{\mathbb{E}_{X_i}[P_{f|X_i}^2] - P_f^2}{P_f(1 - P_f)}$$

- P_f is the solution of reliability analysis
- How about $P_{f|X_i}$?

Two different combination of **Reliability Analysis and Variance Based Sensitivity analysis**:

1. Sobol indices as “by-product” of reliability analysis
 - After FORM reliability analysis
 - After sampling-based reliability analysis
2. Get Sobol indices “before” running reliability analysis
 - Probability model-based GSA

Review of FORM - β and α



β : reliability index

$$P_f = \Phi(-\beta)$$

$$\beta = \|z^*\|$$

$\vec{\alpha}$: importance vector

$$\vec{\alpha} = \frac{\nabla G(z^*)}{\|\nabla G(z^*)\|}, \quad \|\alpha\| = 1 \dots$$

$$\alpha_1^2 + \alpha_2^2 + \dots + \alpha_d^2 = 1.$$

$$\beta = \vec{\alpha} \cdot z^* = \|\alpha\| \|z^*\| = 1 \cdot \beta.$$

Given $\beta, \vec{\alpha}$

$f(z) \sim$ standard normal.

$$G(z) = \nabla G(z^*) (z - z^*) = 0.$$

$$\vec{\alpha} (z - z^*) = 0$$

$$\vec{\alpha} z - \vec{\alpha} z^* = \vec{\alpha} z - \beta = 0$$

FORM and Variance-based Sensitivity Analysis

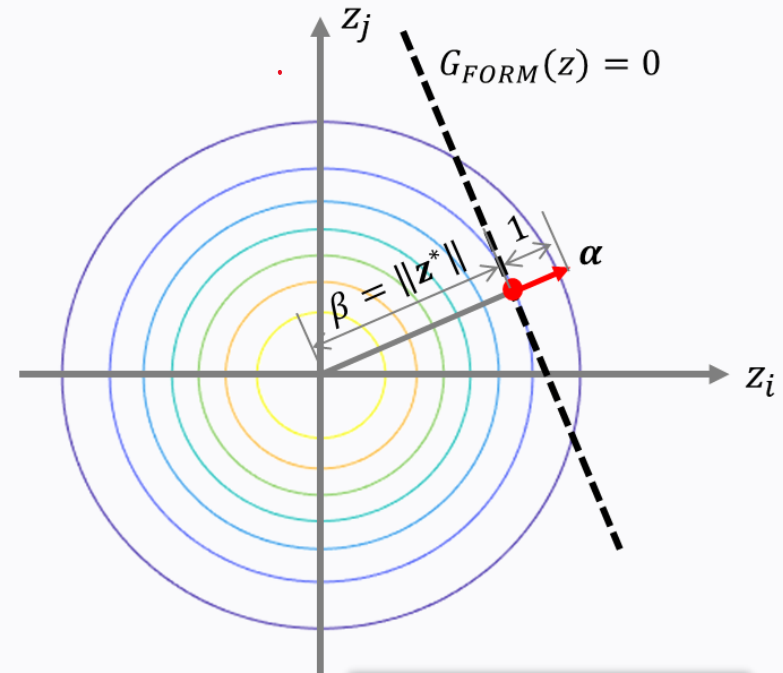
- FORM limit state

$$G_{FORM}(\mathbf{z}) = \nabla G(\mathbf{z}^*)(\mathbf{z} - \mathbf{z}^*)$$

or

$$G_{FORM}(\mathbf{z}) = \beta - \boldsymbol{\alpha}\mathbf{z}$$

Goal: to derive S_i in terms of α_i and β



$$S_i = \frac{\mathbb{E}_{x_i}[P_f^2|x_i] - P_f^2}{P_f(1 - P_f)}$$

$$P_f = \mathbb{P}(\boldsymbol{\alpha}\mathbf{Z} \geq \beta) = \mathbb{P}(\alpha_1 Z_1 + \alpha_2 Z_2 + \dots + \alpha_d Z_d \geq \beta) = \mathbb{P}(\tilde{Z} \geq \beta) = \Phi(-\beta)$$

Standard normal

FORM and Variance-based Sensitivity Analysis

Goal: to derive S_i in terms of α and β

$$P_f = \mathbb{P}(\alpha \mathbf{Z} \geq \beta) = \mathbb{P}(\alpha_1 Z_1 + \alpha_2 Z_2 + \dots + \alpha_d Z_d \geq \beta) = \mathbb{P}(\tilde{Z} \geq \beta) = \Phi(-\beta)$$

$$P_{f|Z_i} = \mathbb{P}(\alpha_i Z_i \geq \beta - \alpha_i Z_i) = \mathbb{P}\left(\tilde{Z} \geq \frac{\beta - \alpha_i Z_i}{\|\alpha_i\|}\right) = \Phi\left(-\frac{\beta - \alpha_i Z_i}{\|\alpha_i\|}\right)$$

$$S_i = \frac{\mathbb{E}_{X_i}[P_{f|X_i}^2] - P_f^2}{P_f(1 - P_f)}$$

FORM and Variance-based Sensitivity Analysis

$$\begin{aligned}
 \mathbb{E}_{z_i}[P_f^2] &= \mathbb{E}_{z_i}[P_{f|z_i}P_{f|z_i}] \\
 &= \mathbb{E}_{z_i} \left[\Phi \left(\frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right) \Phi \left(\frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right) \right] \\
 &= \mathbb{E}_{z_i} \left[\mathbb{P}_{\tilde{z}} \left[\tilde{Z}_1 \leq \frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right] \mathbb{P}_{\tilde{z}} \left[\tilde{Z}_2 \leq \frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right] \right] \\
 &= \mathbb{E}_{z_i} \left[\mathbb{P}_{\tilde{z}} \left[\left(\tilde{Z}_1 \leq \frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right) \cap \left(\tilde{Z}_2 \leq \frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right) \right] \right] \\
 &= \mathbb{P}_{z_i, \tilde{z}} \left[\left(\tilde{Z}_1 \leq \frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right) \cap \left(\tilde{Z}_2 \leq \frac{\alpha_i z_i - \beta}{\|\alpha_{\bar{i}}\|} \right) \right] \\
 &= \mathbb{P}[(\tilde{Y}_1 \leq -\beta) \cap (\tilde{Y}_2 \leq -\beta)] = \Phi_2(-\beta, -\beta; \alpha_i^2)
 \end{aligned}$$

$$S_i = \frac{\mathbb{E}_{X_i}[P_f^2|X_i] - P_f^2}{P_f(1 - P_f)}$$

$$\begin{aligned}
 \tilde{Y}_1 &= \tilde{Z}_1 \|\alpha_{\bar{i}}\| - \alpha_i z_i & \tilde{Y}_1 &\sim N(0,1)^2 \\
 \tilde{Y}_2 &= \tilde{Z}_2 \|\alpha_{\bar{i}}\| - \alpha_i z_i & \tilde{Y}_2 &\sim N(0,1)^2 & \text{corr}[\tilde{Y}_1, \tilde{Y}_2] &= \alpha_i^2
 \end{aligned}$$

FORM and Variance-based Sensitivity Analysis

- Main-effect Sobol index

$$S_i = \frac{\mathbb{E}_{Z_i}[P_f^2|Z_i] - P_f^2}{P_f(1 - P_f)} = \frac{\Phi_2(-\beta, -\beta; \alpha_i^2) - P_f^2}{P_f(1 - P_f)} = \frac{1}{P_f(1 - P_f)} \int_0^{\alpha_i^2} \varphi_2(-\beta, -\beta; r) dr$$

$$\Phi_2(-\beta, -\beta, \|\alpha_v\|^2) = \Phi(-\beta)^2 + \int_0^{\|\alpha_v\|^2} \varphi_2(-\beta, -\beta, r) dr.$$

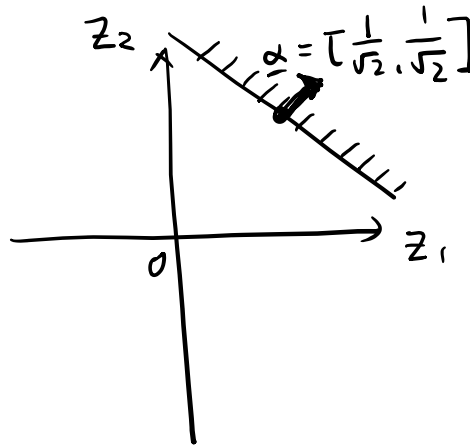
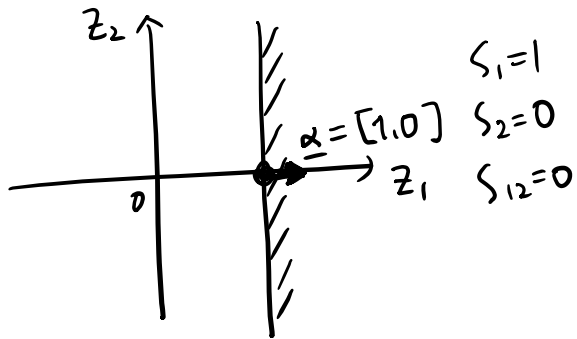
- Total-effect Sobol index

Eq. (32) in [here](#)

$$S_i^T = 1 - \frac{\mathbb{E}_{Z_{\bar{i}}}[P_f^2|Z_{\bar{i}}] - P_f^2}{P_f(1 - P_f)} = 1 - \frac{\Phi_2(-\beta, -\beta; \|\alpha_{\bar{i}}\|^2) - P_f^2}{P_f(1 - P_f)} \\ = \frac{1}{P_f(1 - P_f)} \int_{1-\alpha_i^2}^1 \varphi_2(-\beta, -\beta; r) dr$$

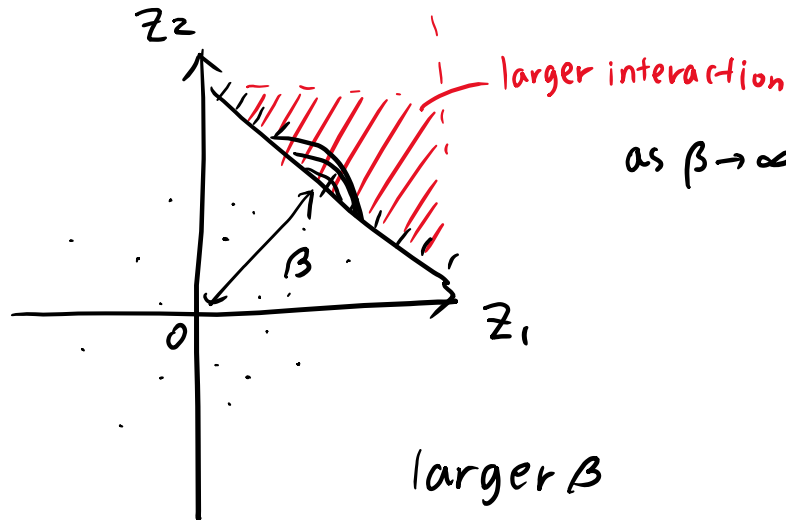
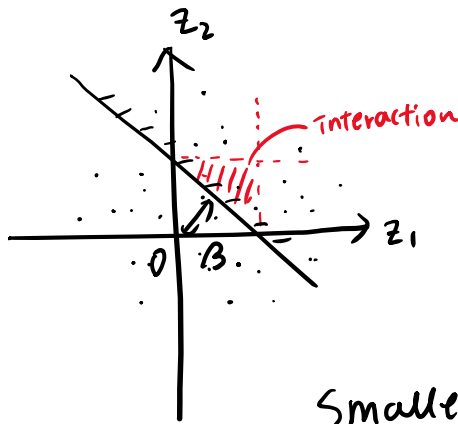
Example with two Random Variables

effect of α



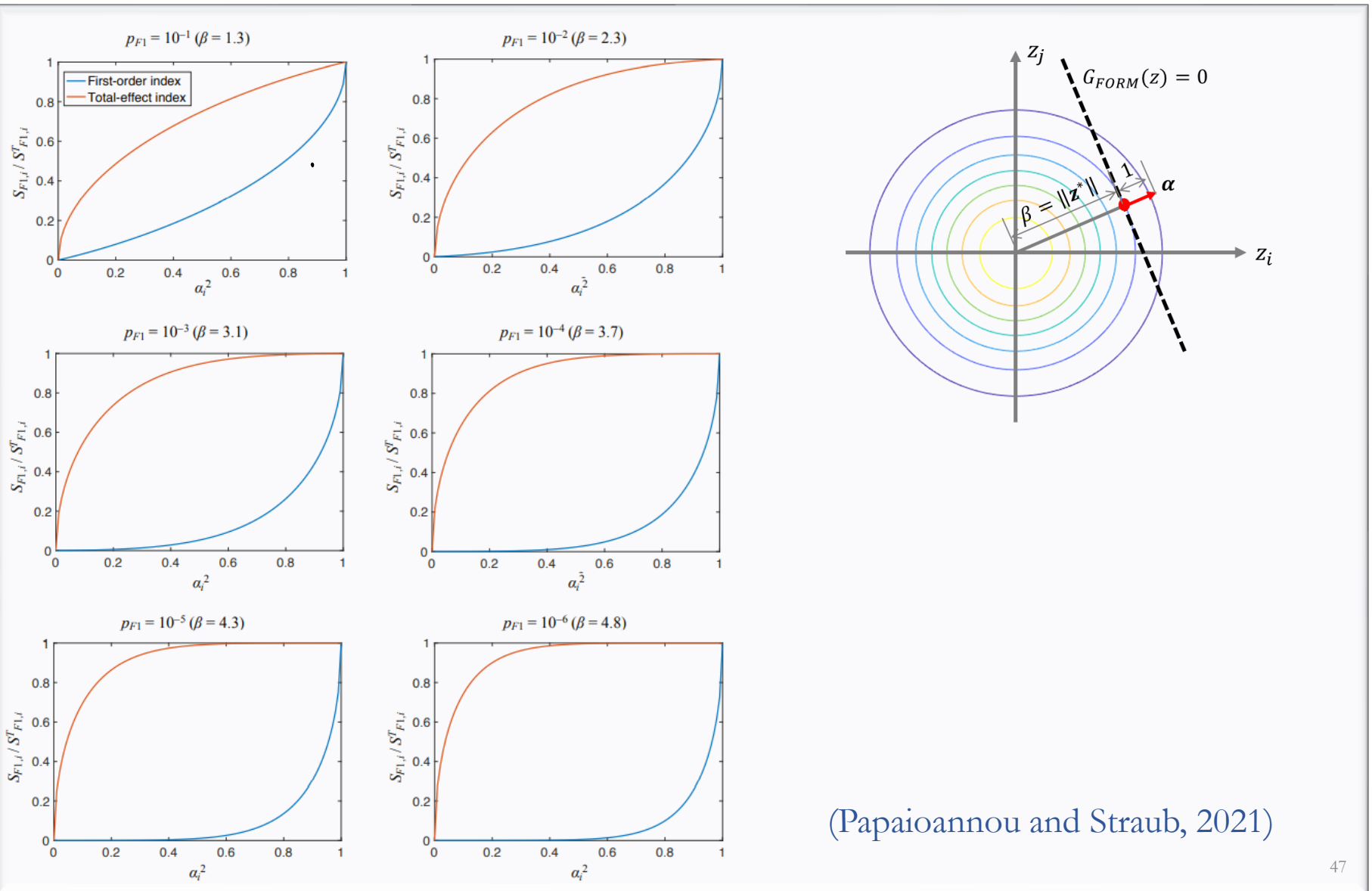
$S_1 = S_2$
 $S_1^T = S_2^T$
 $S_{12} = ??$
 (depends on β)

effect of β

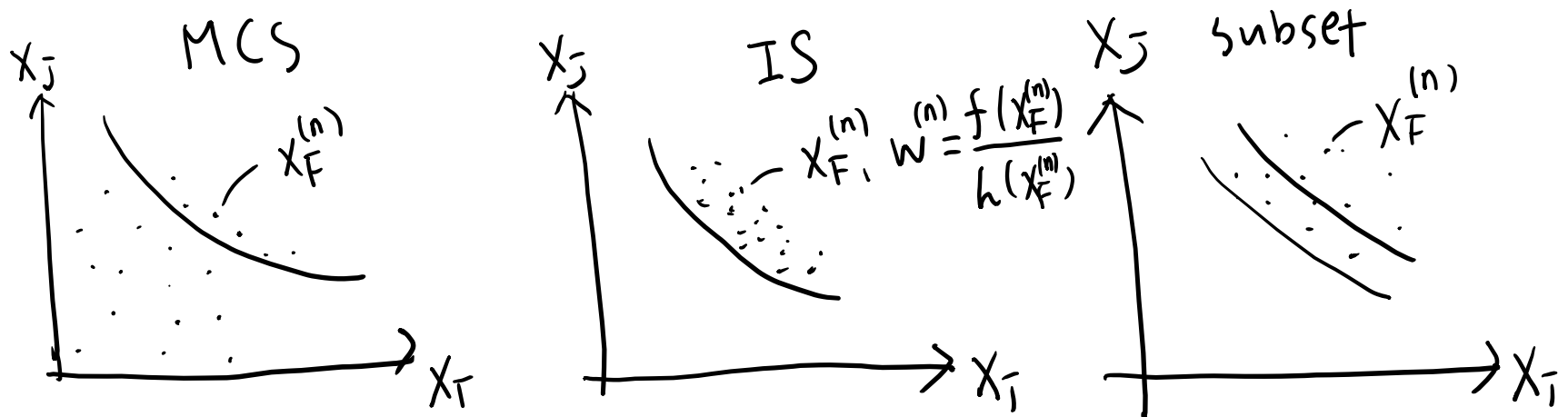


as $\beta \rightarrow \infty$, $\begin{cases} S_i \rightarrow 0 \\ S_i^T \rightarrow 1 \end{cases}$

FORM and Variance-based Sensitivity Analysis



Sampling-based Reliability Analysis and S_i



$$x_F^{(n)} \sim f(\underline{x} | \bar{F})$$

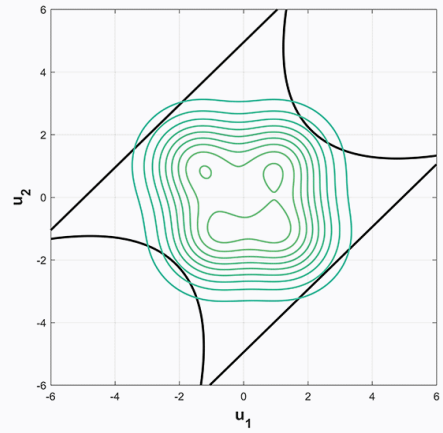
- (1) collect $x_F^{(n)}$ (and $w^{(n)}$)
- (2) fit distribution of $f(\underline{x} | \bar{F})$ using (1)
- (3) calculate S_i, S_i^T using $\hat{f}(\underline{x} | \bar{F})$

Sampling-based Reliability Analysis and S_i

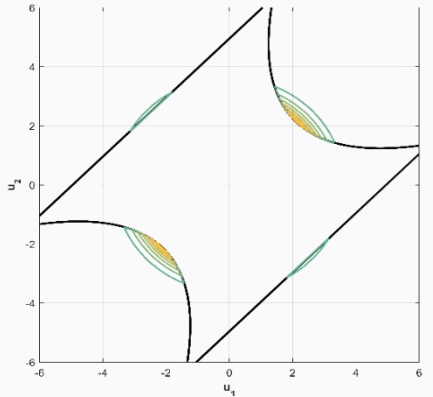
- Again, reformulation of Sobol index

$$\begin{aligned}
 P_{f|X_i} &= \mathbb{P}(\mathcal{F}|X_i) \\
 &= \frac{\mathbb{P}(X_i|\mathcal{F}) \mathbb{P}(\mathcal{F})}{\mathbb{P}(X_i)} \\
 &= \frac{f_{X_i|\mathcal{F}}(X_i) dX_i P_f}{f(X_i) dX_i} \\
 &= \frac{f_{X_i|\mathcal{F}}(X_i) P_f}{f(X_i)}
 \end{aligned}$$

$$S_i = \frac{\mathbb{E}_{X_i}[P_{f|X_i}^2] - P_f^2}{P_f(1 - P_f)}$$



Near-optimal Density

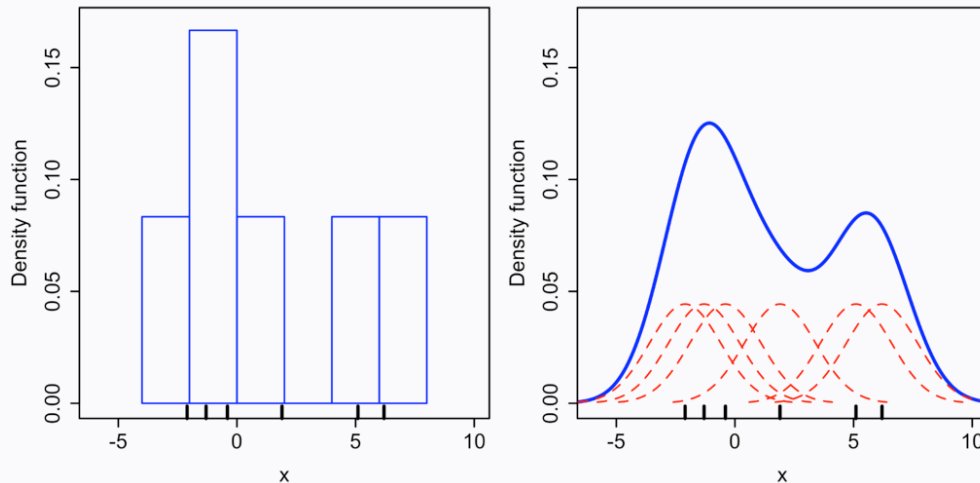


Optimal Density

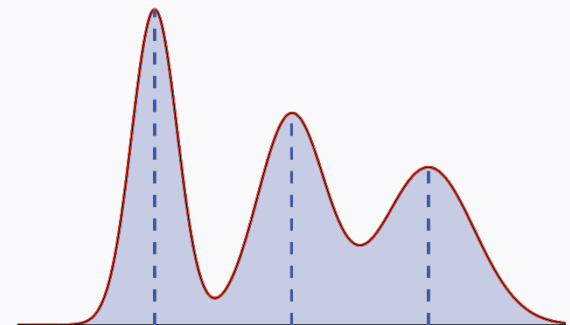
Sampling-based Reliability Analysis and S_i

- Approximation of $f_{X_i|\mathcal{F}}(X_i)$ using kernel density estimation or cross entropy-based distribution fitting

Kernel density estimation



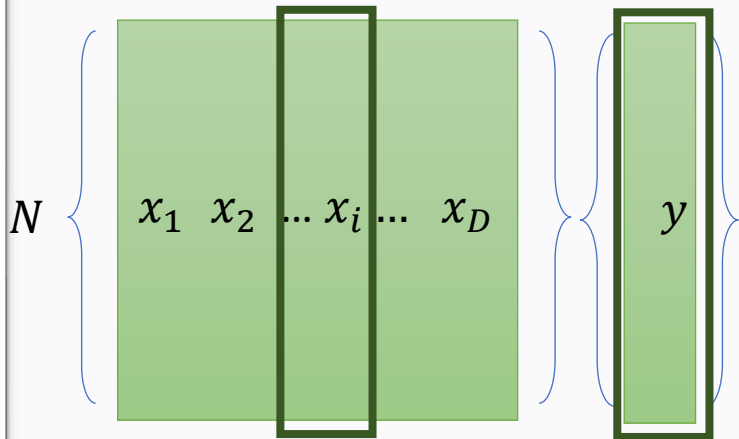
Mixture distribution fitting



- Estimation of total-effect index is more challenging

Sensitivity Analysis before Reliability Analysis

- Probability model-based approach



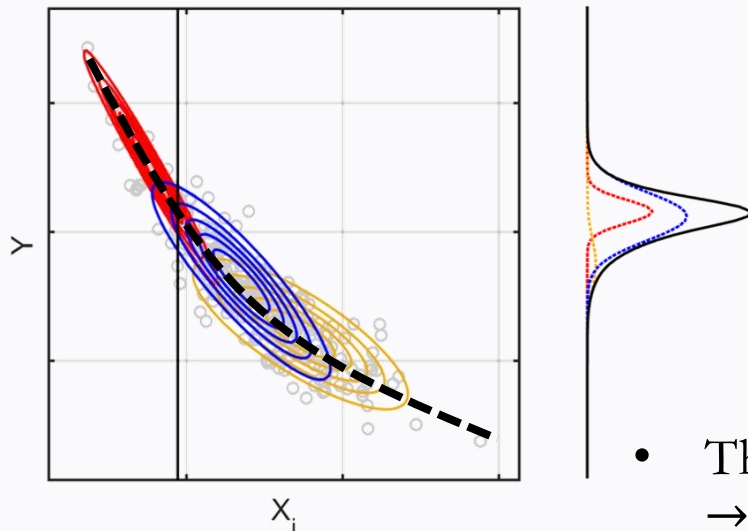
- Let us define

$$Y = G(\mathbf{X})$$

- Approximate joint distribution of $f(X_i, Y)$ using a Gaussian mixture model (GMM)

$$S_i = \frac{\mathbb{E}_{X_i}[P_{f|X_i}^2] - P_f^2}{P_f(1 - P_f)}$$

$$P_{f|X_i} = P(Y \leq 0 | X_i) = \frac{f(X_i, Y \leq 0)}{f(X_i)}$$



$$f(X_i, Y \leq 0) = \int_{-\infty}^0 f_{X_i, Y}(X_i, Y) dY$$

$$f(X_i) = \int_{-\infty}^{\infty} f_{X_i, Y}(X_i, Y) dY$$

- The mixture model “extrapolates” the samples
→ Not accurate for rare events

Toy Example

$$Y = \frac{2p}{Eb^3} \left[(4 + 5\nu) \frac{h^2L}{4} + 2L^3 \right],$$

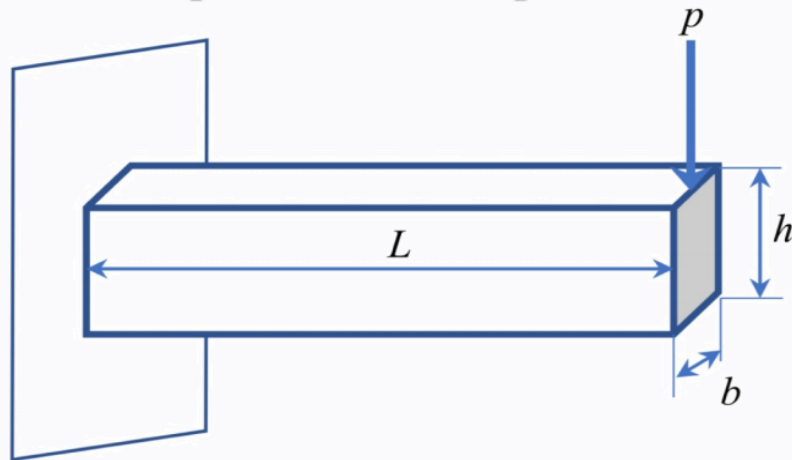
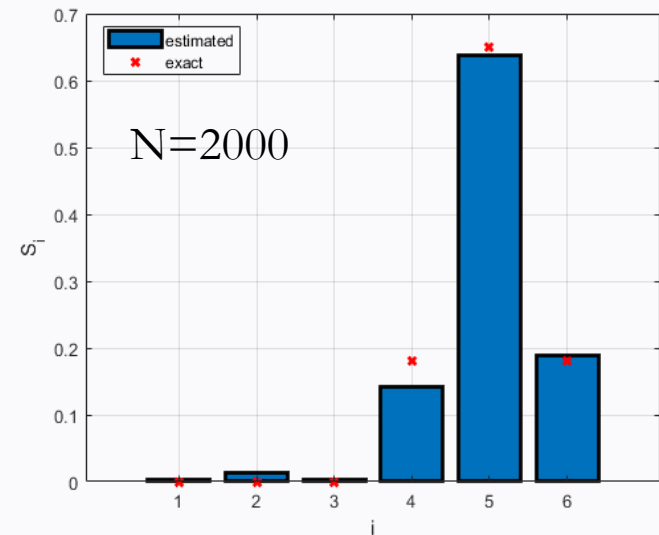
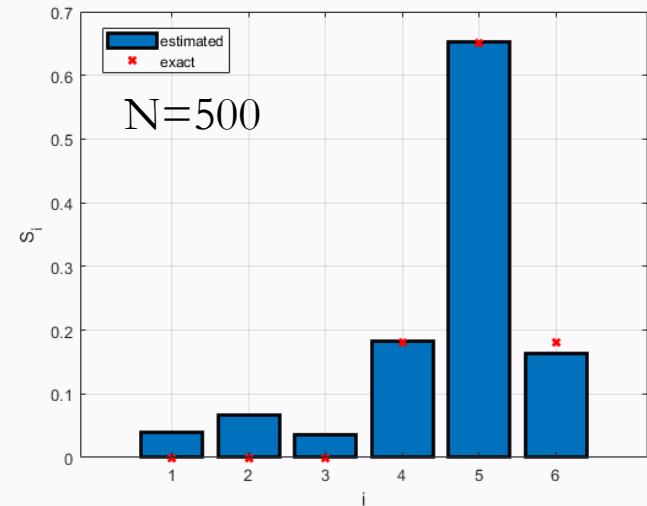


Fig. 11. A cantilever beam.

Table 1
Random variables of the cantilever beam example.

Variable	p (kN)	ν	b (m)	h (m)	L (m)
Distribution	Normal	Normal	Lognormal	Lognormal	Lognormal
Mean	65	0.225	0.2	0.3	1.5
Standard deviation	0.5	0.03	0.02	0.02	0.05

$$f_E(e) = 0.4N(e, 200, 1) + 0.6N(e, 190, 0.95^2),$$



Truss Model

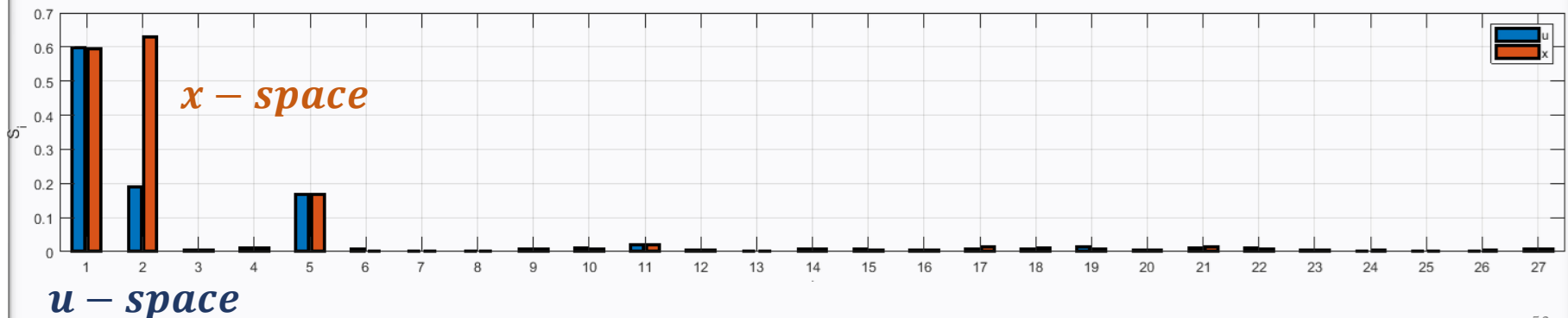
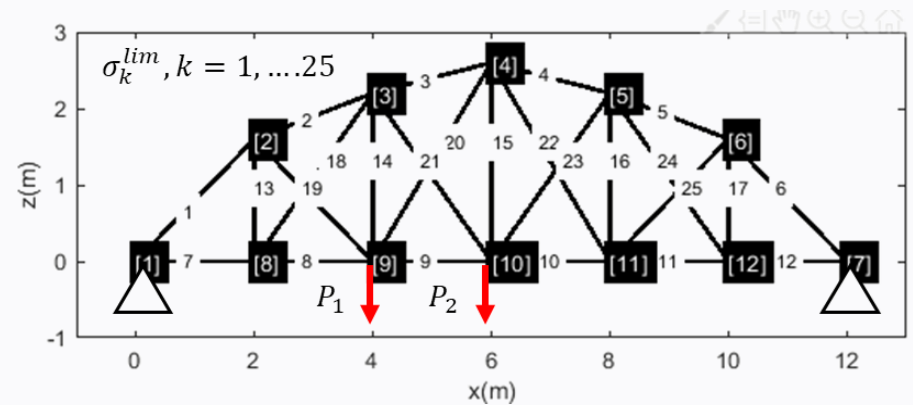
Input variables

x_1, x_2 : load1 (P_1) and load2 (P_1) with (correlation 0.6)

$x_3 \sim x_{27}$: strength of each member, lognormal

Output variable: limit state function

$$g(x) = \min_{k=1, \dots, 25} (\sigma_k^{\text{thr}} - |\sigma_k(P_1, P_2)|)$$



Examples

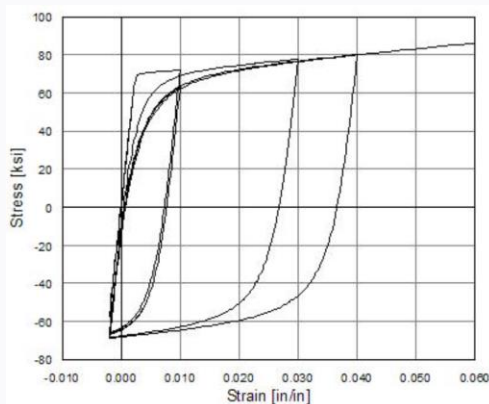
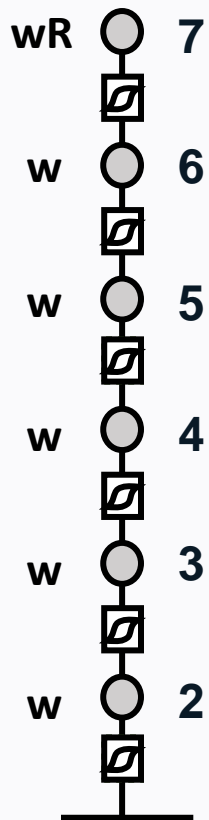
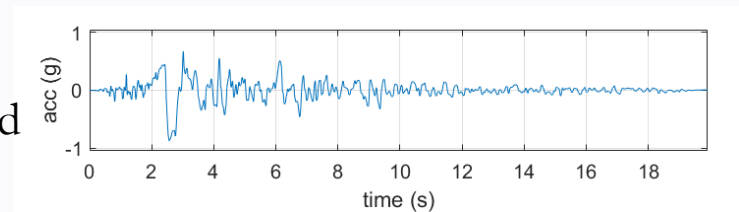
- Structural model: Shear building (OpenSees)

- Input parameters

Name	Mean	C.O.V
w	100	0.1
wR	50	0.1
k	326	0.1
Fy	50	0.1
alpha	0.2	0.1
factor (PGA)	0.1	0.1

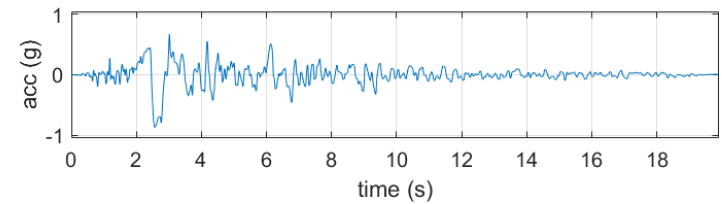
- Excitation

Rinaldi
near-field

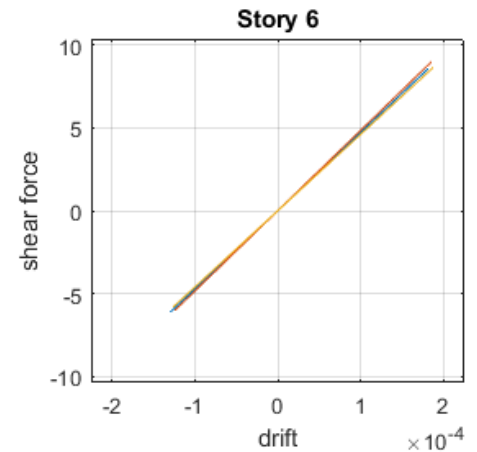
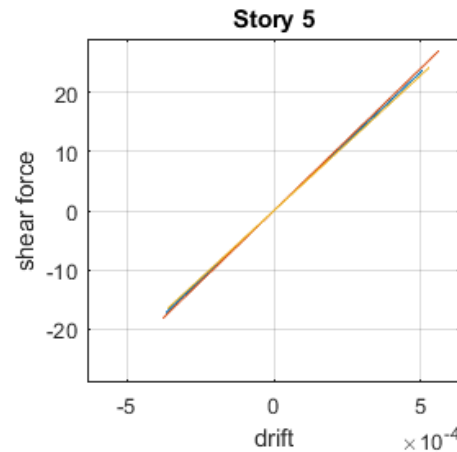
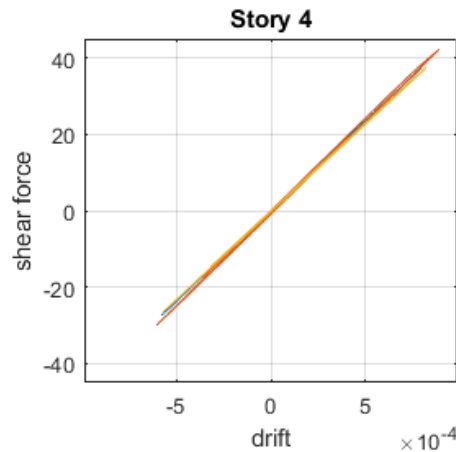
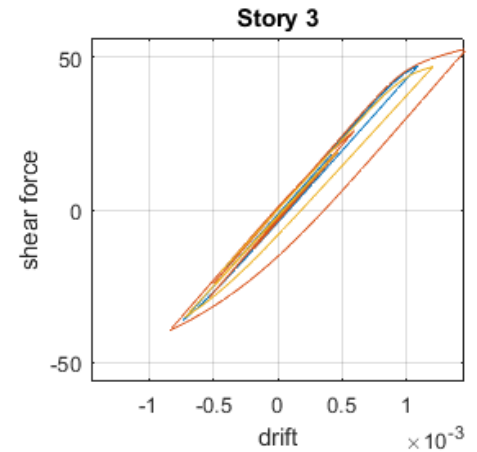
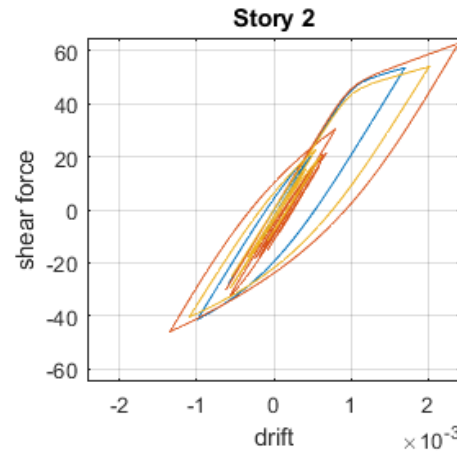
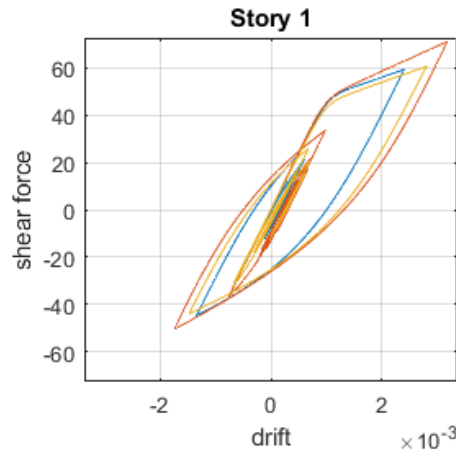
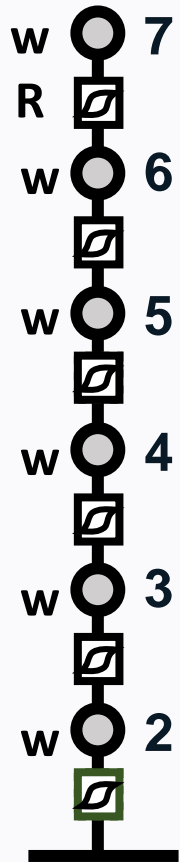


Steel 02 Material

Nonlinear behavior

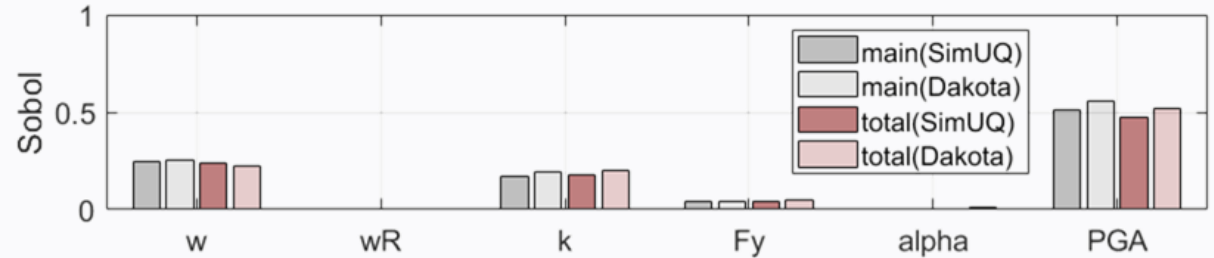


- Hysteresis curves for Rinaldi UQ

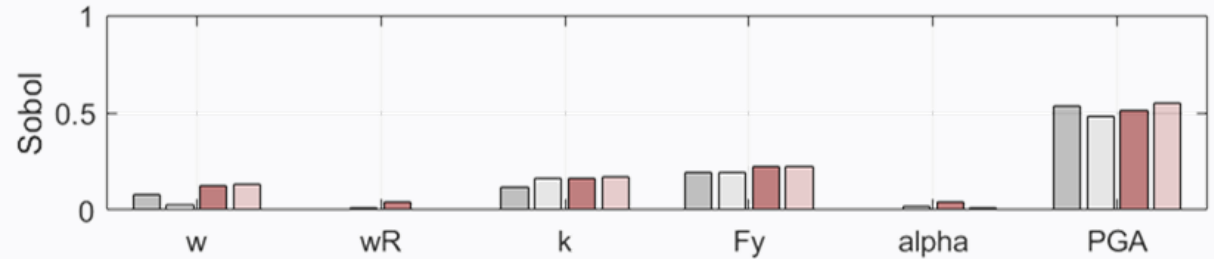


Examples

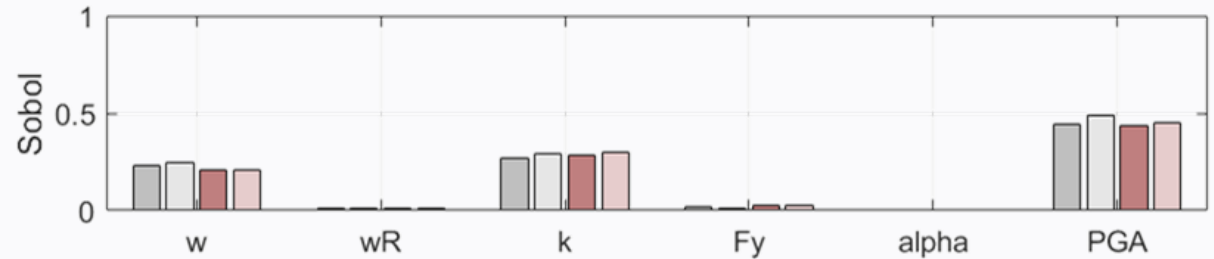
node2 disp



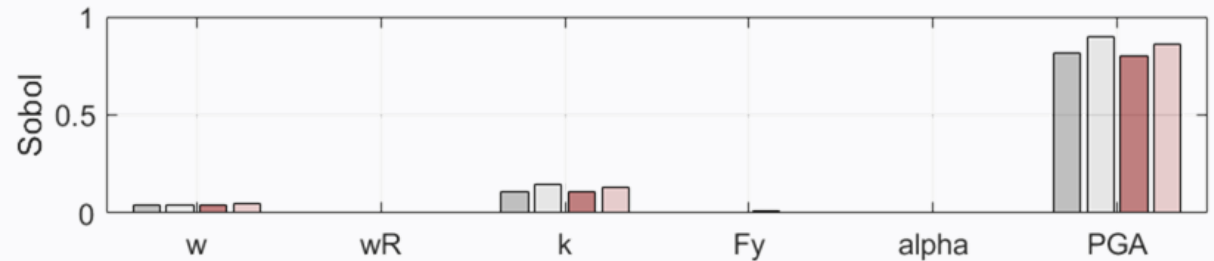
node2 acc



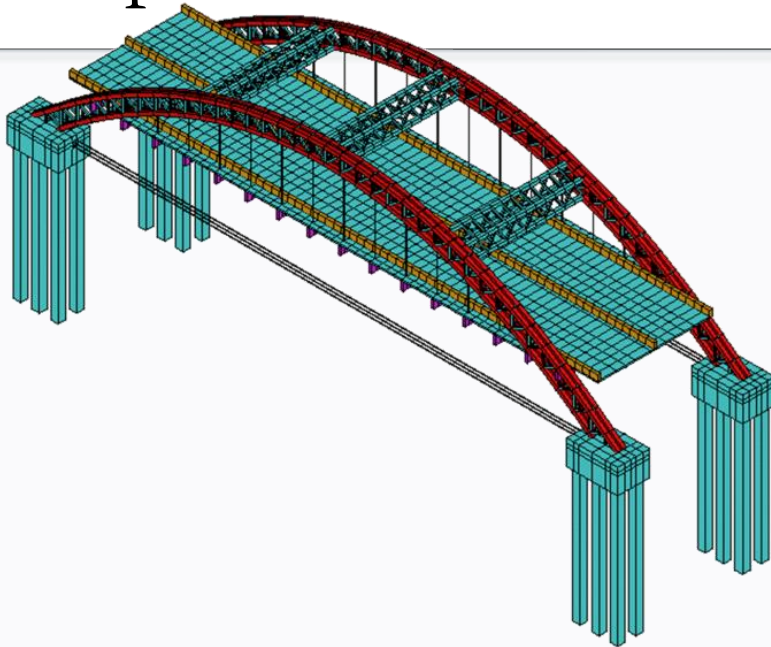
node7 disp



node7 acc



Examples: Parameter selection in FE model updating



GSA is performed for 15 parameters

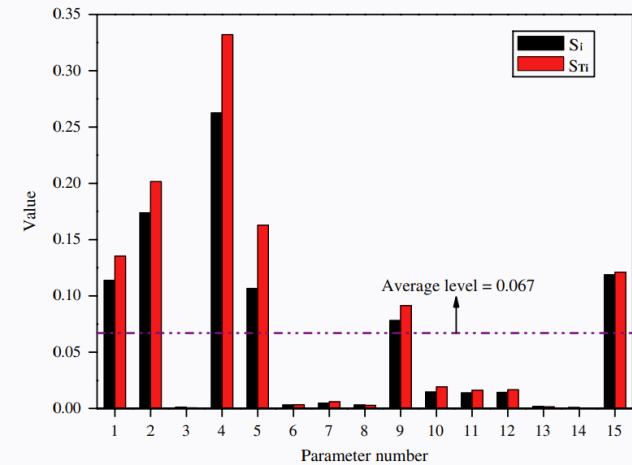


Table 4. Parameters Range of the Arch Bridge in Hertz

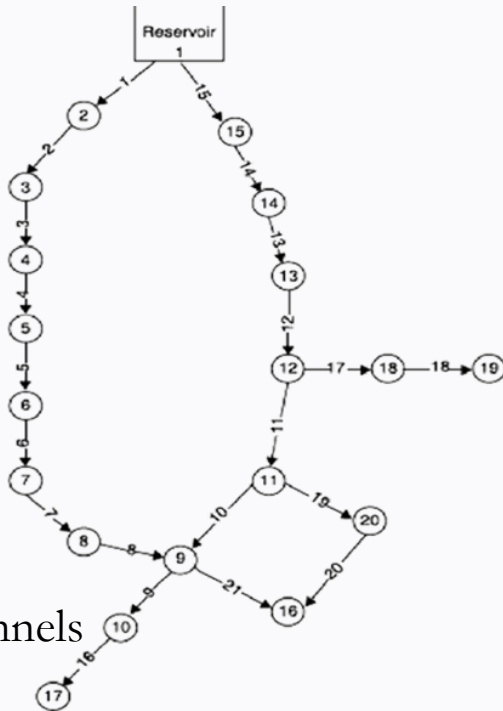
Number	Parameter	Nominal value	Lower bound	Upper bound
1	Elastic modulus of steel used in hollow tube	2.10×10^{11} Pa	1.47×10^{11} Pa	2.73×10^{11} Pa
2	Elastic modulus of concrete filled tubular arch rib	4.560×10^{10} Pa	3.192×10^{10} Pa	5.928×10^{10} Pa
3	Moment of inertia of concrete filled tubular arch rib	0.0147196 m ⁴	0.01030372 m ⁴	0.01913548 m ⁴
4	Density of concrete filled tubular arch rib	2,871.14 kg/m ³	2,009.798 kg/m ³	3,732.482 kg/m ³
5	Sectional area of concrete filled tubular arch rib	0.4311 m ²	0.30177 m ²	0.56043 m ²
6	Elastic modulus of wall above deck	2.850×10^{10} Pa	1.995×10^{10} Pa	3.705×10^{10} Pa
7	Density of wall above deck	2,500 kg/m ³	1,750 kg/m ³	3,250 kg/m ³
8	Elastic modulus of deck	3.0×10^{10} Pa	2.1×10^{10} Pa	3.9×10^{10} Pa
9	Density of deck	2,500 kg/m ³	1,750 kg/m ³	3,250 kg/m ³
10	Thickness of deck	0.25 m	0.2 m	0.3 m
11	Elastic modulus of cross girder	3.450×10^{10} Pa	2.415×10^{10} Pa	4.485×10^{10} Pa
12	Moment of inertia of cross girder about major axis	0.0756 m ⁴	0.05292 m ⁴	0.09828 m ⁴
13	Sectional area of suspender	0.002494 m ²	0.0017458 m ²	0.0032422 m ²
14	Sectional area of prestressed cable	0.0044428 m ²	0.00310996 m ²	0.00577564 m ²
15	Spring stiffness in lateral direction	5.0×10^5 N/m	3.5×10^5 N/m	6.5×10^5 N/m

“(..) Parameters 3, 6, 7, 8, 13, and 14 should be excluded from the parameter candidates because they have little influence over the objective function.”

Examples:

Reducing the complexity of multi-objective optimization

Multi-objective Water Distribution System Optimization



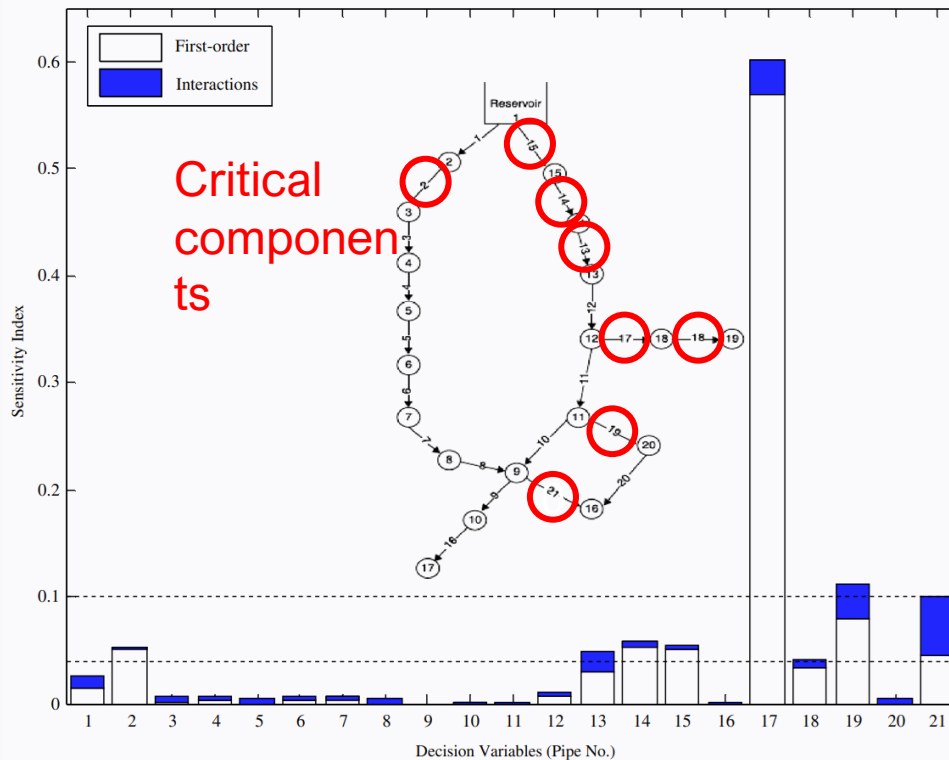
New York Tunnels
Rehabilitation
(21 components)

- 21 pipes in a system
- 16 Retrofitting options of each pipe :
 - 15 available diameters ranging 0.914 - 5.182 m
 - Do nothing
- Conflicting objectives:
 - Cost: capital cost (pipes, tanks, and pumps) + operating cost during a design period
 - Performance:
eg. surplus power energy per unit weight

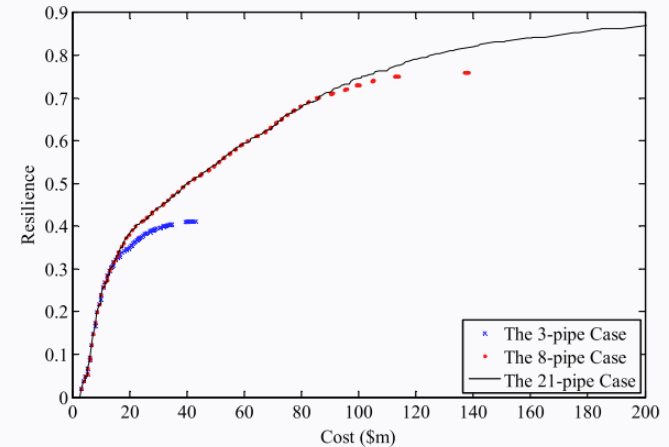
Goal: **Maximize** the performance, **minimize** the cost

Examples: Multi-objective Water Distribution System Optimization

First-order and total-order indices



Best Pareto fronts



Convergence rate

